

**Request for an Incidental Harassment  
Authorization to Allow the Non-Lethal Take of  
Marine Mammals Incidental to Site  
Characterization Surveys of BOEM Lease Area  
OCS-A 0521**

**Submitted To**

**National Marine Fisheries Service  
Office of Protected Resources  
Silver Spring, MD**

**Submitted By**

**Mayflower Wind Energy LLC**



**MAYFLOWER WIND**

**Revised April 2020**

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## TABLE OF CONTENTS

<b>1.0</b>	<b>DESCRIPTION OF SPECIFIED ACTIVITY .....</b>	<b>1</b>
1.1.	HRG SURVEY DETAILS .....	1
1.2.	SURVEY SOUND SOURCES .....	3
1.3.	GEOTECHNICAL SURVEY .....	5
1.4.	VESSEL DYNAMIC POSITIONING .....	5
<b>2.0</b>	<b>DATES, DURATION, AND SPECIFIED GEOGRAPHIC REGION.....</b>	<b>6</b>
<b>3.0</b>	<b>SPECIES AND NUMBERS OF MARINE MAMMALS .....</b>	<b>6</b>
<b>4.0</b>	<b>AFFECTED SPECIES STATUS AND DISTRIBUTION .....</b>	<b>12</b>
4.1.	CETACEANS .....	12
4.1.1.	<i>Fin Whale (Balaenoptera physalus)</i> .....	12
4.1.2.	<i>Humpback Whale (Megaptera novaeangliae)</i> .....	13
4.1.3.	<i>Common Minke Whale (Balaenoptera acutorostrata)</i> .....	14
4.1.4.	<i>North Atlantic Right Whale (Eubalaena glacialis)</i> .....	15
4.1.5.	<i>Sei Whale (Balaenoptera borealis)</i> .....	17
4.1.6.	<i>Atlantic White-Sided Dolphin (Lagenorhynchus acutus)</i> .....	18
4.1.7.	<i>Common Bottlenose Dolphin (Tursiops truncatus)</i> .....	19
4.1.8.	<i>Harbor Porpoise (Phocoena phocoena)</i> .....	20
4.1.9.	<i>Pilot Whales (Globicephala spp.)</i> .....	20
4.1.10.	<i>Risso’s Dolphin (Grampus griseus)</i> .....	21
4.1.11.	<i>Short-beaked Common Dolphin (Delphinus delphis delphis)</i> .....	22
4.1.12.	<i>Sperm Whale (Physeter macrocephalus)</i> .....	23
4.2.	PINNIPEDS .....	24
4.2.1.	<i>Gray Seal (Halichoerus grypus)</i> .....	24
4.2.2.	<i>Harbor Seal (Phoca vitulina vitulina)</i> .....	25
<b>5.0</b>	<b>TYPE OF INCIDENTAL TAKING AUTHORIZATION REQUESTED.....</b>	<b>26</b>
<b>6.0</b>	<b>TAKE ESTIMATES FOR MARINE MAMMALS.....</b>	<b>26</b>
6.1.	BASIS FOR ESTIMATING POTENTIAL “TAKE” .....	27
6.2.	ACOUSTIC THRESHOLDS .....	27
6.3.	AREA POTENTIALLY EXPOSED TO SOUNDS ABOVE THRESHOLD LEVELS .....	29
6.3.1.	<i>Level A</i> .....	29
6.3.2.	<i>Level B</i> .....	30
6.4.	MARINE MAMMAL DENSITIES.....	32
6.5.	REQUESTED TAKE .....	34
<b>7.0</b>	<b>ANTICIPATED IMPACT OF THE ACTIVITY .....</b>	<b>36</b>
<b>8.0</b>	<b>ANTICIPATED IMPACTS ON SUBSISTENCE USES .....</b>	<b>37</b>
<b>9.0</b>	<b>ANTICIPATED IMPACTS ON HABITAT .....</b>	<b>37</b>
<b>10.0</b>	<b>ANTICIPATED EFFECTS OF HABITAT IMPACTS ON MARINE MAMMALS.....</b>	<b>37</b>
<b>11.0</b>	<b>MITIGATION MEASURES TO PROTECT MARINE MAMMALS AND THEIR HABITAT .....</b>	<b>38</b>
11.1.	PROTECTED SPECIES MONITORING.....	38
11.1.1.	<i>PSO/PAM Watch Guidelines</i> .....	38
11.1.2.	<i>Day-time Visual Monitoring Equipment</i> .....	38
11.1.3.	<i>Night-time Visual Monitoring Equipment</i> .....	38
11.1.4.	<i>Passive Acoustic Monitoring</i> .....	38

11.1.5. Data Collection and Reporting .....39

11.1.6. Mitigation Measures.....39

11.1.7. Vessel Strike Avoidance.....40

11.1.8. Sound Source Verification .....41

**12.0 MITIGATION MEASURES TO PROTECT SUBSISTENCE USES .....41**

**13.0 MONITORING AND REPORTING .....41**

**14.0 SUGGESTED MEANS OF COORDINATION .....41**

**15.0 LITERATURE CITED .....42**

**APPENDIX A – DISTANCES TO LEVEL A ACOUSTIC THRESHOLDS.....52**

**APPENDIX B – DISTANCES TO LEVEL B ACOUSTIC THRESHOLDS .....69**

## LIST OF ACRONYMS

~	approximately
ADC	analogue-digital converter
AMAPPS	Atlantic Marine Assessment Program for Protected Species
BIA	Biologically Important Area
BOEM	Bureau of Ocean Energy Management
CETAP	Cetacean and Turtle Assessment Program
CPT	cone penetration test
dB	decibel
DMA	Dynamic Management Area
DP	dynamic positioning
<i>e.g.</i>	for example
EEZ	Exclusive Economic Zone
ESA	Endangered Species Act
hr	hour
HRG	high-resolution geophysical
ITA	Incidental Take Authorization
IR	infrared
IWC	International Whaling Commission
kHz	kilohertz
kJ	kilo-Joule
km	kilometer
LED	light-emitting diode
m	meter
MA WEA	Massachusetts Wind Energy Area
MBES	multibeam echo sounder
MMPA	Marine Mammal Protection Act
NARW	North Atlantic right whale
NEFSC	NOAA Northeast Fisheries Science Center
NLPSC	Northeast Large Pelagic Survey Collaborative
NMFS	National Marine Fisheries Service
NVD	night vision device
OCS	Outer Continental Shelf
OSP	optimum sustainable population
PAM	passive acoustic monitoring
PSO	protected species observer
RI/MA WEAs	Rhode Island and Massachusetts Wind Energy Areas
re 1 $\mu$ Pa	referenced to one micro Pascal
RL	received level
RWSAS	Right Whale Sightings Advisory System
SEFSC	NOAA Southeast Fisheries Science Center
SEL	sound exposure level
SMA	Seasonal Management Area
SPL	sound pressure level
SPL <sub>rms</sub>	root-mean-square sound pressure level

SPL <sub>cum</sub>	cumulative sound pressure level
SSS	side scan sonar
UME	unusual mortality event
USFWS	United States Fish and Wildlife Service
WTG	wind turbine generator

## 1.0 DESCRIPTION OF SPECIFIED ACTIVITY

Mayflower Wind Energy LLC (Mayflower) is a joint venture between Shell New Energies US LLC (Shell) and EDPR Offshore North America LLC (EDPR) co-owned on a 50:50 basis. In December 2018, Mayflower was awarded the BOEM ATL-4W OCS-A 0521 Lease Area (hereafter, the Lease Area), off the coast of Massachusetts, which covers approximately 127,388 acres. Lease Area OCS-A 0521 is located on the OCS approximately 60 km south of Martha's Vineyard, MA. Mayflower intends to conduct a marine site characterization survey of the Lease Area as well as the export cable route from the Lease Area to landfall at Falmouth, MA, commencing in April 2020. The objective of the survey is to acquire geotechnical and high resolution geophysical (HRG) data on the bathymetry, seafloor morphology, subsurface geology, environmental/biological sites, seafloor obstructions, soil conditions, and locations of any man-made, historical or archaeological resources within Lease Area OCS-A 0521 to support lease development in accordance with Bureau of Ocean Energy Management (BOEM) renewable energy regulations and associated guidelines pursuant to 30 CFR Part 585 as well as state of Massachusetts requirements.

The total duration of geophysical survey activities would be approximately 348 vessel-days, with up to three vessels operating concurrently—one operating primarily in the Lease Area and deep-water sections of the cable route (24 hours/day for ~168 days), a second operating along the shallow water portion of the cable route (12 hours/day for ~150 days), and a third, shallow-draft vessel may be used in very shallow waters (12 hours/day for ~30 days). The estimated total days for each vessel include allowances for weather downtime as well as crew transfers. Up to two additional vessels may be used simultaneously to the geophysical survey vessels for geotechnical sampling activities (vibracores, seabed core penetration tests (CPTs), and boreholes, operating 24 hours/day). The total duration of geotechnical sampling activities and HRG surveying from start of mobilization through completion of offshore fieldwork is anticipated to be 6 months, including weather standby time.

This IHA Application is intended to address survey operations from June 1 through September 30. For the anticipated vessel days that will occur under the IHA, please see Table 1.

### 1.1. HRG Survey Details

Figure 1 shows the overall HRG survey area including the Lease Area and the planned export cable route from the Lease Area to landfall at Falmouth, MA. The survey has been divided into two areas:

- (1) The orange shaded area in Figure 1 shows the Lease Area where wind turbine generators (WTGs) and inter-array cables will be installed as well as the deep-water section of the export cable route. The proposed survey in this area will consist of 24-hour vessel operations starting in April under lease stipulations and continuing under an IHA.
- (2) The green section in Figure 1 shows the rest of the export cable route in shallower nearshore waters. Survey operations along this route will primarily consist of a shallow-water vessel operating HRG equipment only during daylight hours on favorable weather days starting in April under lease stipulations and continuing under an IHA. A shallow draft (<5 m) vessel may be used to complete near-shore HRG surveys of the cable route in very shallow waters (operating only during daylight hours for ~30 days).

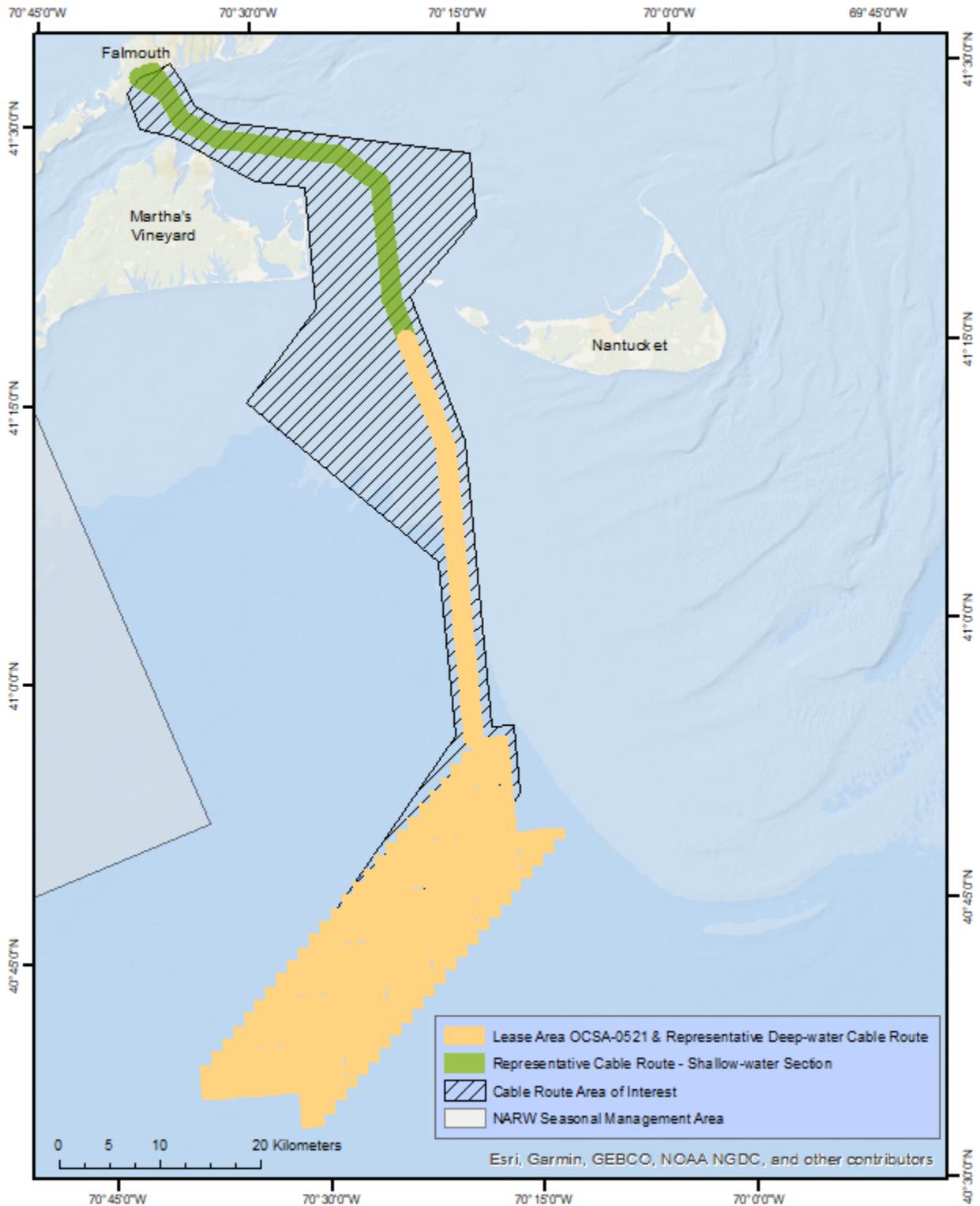


Figure 1. Map of Mayflower Wind Lease OCS-A 0521 within the Massachusetts Wind Energy Area and the proposed export cable route to Falmouth, MA.

Table 1. Activity Details for 2020 Mayflower Geophysical and Geotechnical Surveys from June 1 through September 30.

Activity	Location	Activity Level <sup>1</sup>	Vessel	Operating Schedule	Total Vessel Days	Active Sound Source Days
HRG Survey	Lease Area and Deepwater section of the cable route	~9,900 line km	#1	24 hrs/day	122	90
	Shallow-water section of the cable route	~5,225 line km	#2	Daylight only	122	95
	Very shallow cable route	~1,650 line km	#3	Daylight only	30	30
Geotechnical Survey	Lease Area and Deepwater section of the cable route	195 samples	#4	24 hrs/day	122	0
	Shallow-water section of the cable route	85 samples	#5	24 hrs/day	79	0

<sup>1</sup>Activity level for HRG Surveys was calculated by multiplying the Active Sound Source Days by the estimated km/day to be surveyed in 24 hrs (110 km) or during daylight (55 km).

- Vessel #1: Large, deep-water capable geophysical/geotechnical survey vessel; may also operate in shallow-water areas depending on water depths and vessel schedules
- Vessel #2: Shallow water geophysical/geotechnical survey vessel
- Vessel #3: Small, shallow draft (<5 m) geophysical/geotechnical survey vessel (optional)
- Vessel #4: Large, deep-water capable geotechnical survey vessel (#4/#5 may be a single vessel)
- Vessel #5: Shallow water geotechnical survey vessel (#4/#5 may be single a vessel)

## 1.2. Survey Sound Sources

The following survey sensors and equipment may be utilized during this survey:

### Geophysical Equipment

- Sub-bottom Profilers
  - Innomar SES-2000 Medium-100 parametric SBP and/or
  - Edgetech 3100 with SB-216 towfish
- Sparkers
  - Geomarine Geo-Spark Ultra Hi-Res Sparker System with 400 tip Geo-Source operated at 800 J input voltage
  - Multi-Trace 48 channel integrated in Streamer Reel (75 m)
  - Geo-Sense Light Weight 8 Element Single Channel Streamer
- Multibeam Echosounders
  - Dual-head Kongsberg EM 2040 and/or
  - Teledyne Seabat T50
- Sidescan Sonars
  - EdgeTech 4200 300/600 kHz and/or
  - EdgeTech 4205 300/600/900 kHz

### Navigational Systems

- Ultra-Short Baseline (USBL) acoustic tracking system and beacons
  - HiPAP 351, 352, 500, 501, or 502 and/or
  - IXSEA GAPS and/or
  - Easy Track Nexus2 USBL and/or
  - Sonardyne Ranger 1, 2, and/or
  - Scout Pro USBL Acoustic Positioning System
- Surface Navigation including DGNS/Gyrocompass/Attitude Sensors

**Geotechnical and Benthic Systems**

- Alpine Model P 4 inch Vibracore
- Datem Neptune 3000 CPT
- Geoquip Marine GMC201 CPT
- WISON-APB downhole CPT
- Geometrics G-882 Marine Magnetometer Transverse Gradiometer Array
- Grab Sampler with Camera
- SPI/PVI Camera System

Some of the sounds produced during the planned surveys have the potential to be audible to marine mammals (MacGillivray et al. 2014). Representative sound-generating equipment that will be used during the geophysical surveys is shown in Table 2 and Table 3. Only the equipment in Table 2 produces sounds that fall within the range of marine mammal hearing (see Section 6) and thus has the potential to result in behavioral harassment. Although USBL systems produce sounds audible to some marine mammals, they are used for navigational and positioning purposes during HRG surveys and are not considered to have the potential to result in take (NMFS 2019 communication regarding Mayflower Surveys). Equipment shown in Table 3 has operating frequencies that exceed the upper frequency range of marine mammal hearing and thus are not considered when estimating potential takes.

Table 2. 2020 Mayflower Wind Geophysical Survey Equipment with Operating Frequencies Below 200 kHz.

Equipment Type	System	Operating Frequency
Sub-bottom Profiler	Innomar SES-2000 Medium SBP	Primary frequencies: ~100kHz (band 85 – 115kHz) Secondary low frequencies (band 2 – 22 kHz)
	Edgetech 3100 with SB-2-16S towfish	2 – 16 kHz
Sparker	Geomarine Geo-Spark 800 J system	0.25 – 5 kHz

Table 3. 2020 Mayflower Wind Geophysical Survey Equipment with Operating Frequencies Above 200 kHz and Geotechnical Survey Equipment.

Equipment Type	System	Operating Frequency
Sidescan Sonar	EdgeTech 4200	300/600 kHz
	EdgeTech 4205	300/600/900 kHz
Multibeam Echosounder	Dual-head Teledyne SeaBat T50	200-400 kHz variable
	Dual-head Kongsberg EM 2040	200-400 kHz
Surface Navigation including DGNSS/Gyrocompass/Attitude Sensors	Applanix POSMV & Veripos Apex	N/A
CTD/SVP	Teledyne rapidCast	N/A
Surface Navigation including DGNSS/Gyrocompass/Attitude Sensors	Applanix POSMV & Veripos Apex	N/A
Gradiometer	Geometrics G-882 Marine Magnetometer Transverse Gradiometer Array	N/A
Vibracore	Alpine Model P 4 inch	N/A
CPT	Dalem Neptune 3000	N/A
	Geoquip Marine GMC201	N/A
	WISON-APB (downhole)	N/A

### 1.3. Geotechnical Survey

Within the Lease Area, a ~20-week geotechnical campaign including vibracores, seabed CPT and borehole sampling conducted by one or two additional vessels (#4 and #5 in Table 1) will also take place in 2020. Additionally, vibracores may be collected along the deep-water section of the export cable route and along the shallow-water section of the cable route. For the anticipated vessel days that will occur under the IHA, please see Table 1. Camera systems that will be used for visual surveys of the seafloor and shallow sub-surface in all survey areas do not produce sounds. Geotechnical sampling will be conducted from a vessel with a Dynamic Positioning (DP) system.

During geotechnical surveying, sounds produced by vibracoring and CPT are within marine mammal hearing ranges. However, NMFS recently reported that the likelihood of vibracoring sounds rising to the level of take is so low as to be discountable because of the short duration of the activity and the fact that marine mammals are expected to react to the vessel and DP sounds before the vibracoring starts (e.g., NMFS 2018b, c, d). NMFS also reported recently that field studies have shown that CPT sounds are unlikely to exceed marine mammal acoustic harassment thresholds and are thus unlikely to result in takes (e.g., NMFS 2018b, c, d). Thus, the geotechnical sampling is not anticipated to result in marine mammal take and therefore is not considered further in this application.

### 1.4. Vessel Dynamic Positioning

Vessels conducting geotechnical surveys use DP systems to maintain vessel position at specific locations during sampling activities. DP systems use bow-thrusters that create non-impulsive sounds that

are similar to other vessel sounds like the vessel's main propeller(s). Although DP thruster sounds are within marine mammal hearing ranges, NMFS reported recently that monitoring of past projects during DP thruster use has shown a lack of behavioral response to these sounds by marine mammals and thus the probability that DP thruster use would result in marine mammal take is so low as to be discountable (e.g., NMFS 2018b, c, d). Vessel DP use is therefore not considered further in this application.

## 2.0 DATES, DURATION, AND SPECIFIED GEOGRAPHIC REGION

Mayflower's 2020 site characterization survey will occur within BOEM Renewable Energy Lease Area OCS-A 0521 offshore Massachusetts and along the proposed export cable route from the Lease Area to landfall at Falmouth, MA (Figure 1). The Lease Area comprises approximately 127,388 acres (515.5 km<sup>2</sup>) and lies approximately 20 nautical miles (38 km) south-southwest of Nantucket. Water depths within the Lease Area are in the range of 126–204 ft (38–62 m).

The survey is expected to begin in April 2020. Inclusive of any weather downtime and crew transfers, and allowing for 24-hour operations within the Lease Area and deep-water portion of the export cable route, the planned survey activities should be completed in a 6-month period. This includes two vessels operating concurrently for a combined total of 328 vessel-days and up to three additional vessels operating concurrently for a combined total of up to 254 vessel-days. This IHA application is intended to cover planned operations from June 1 through September 30 (see Table 1).

## 3.0 SPECIES AND NUMBERS OF MARINE MAMMALS

Table 4 lists the 26 marine mammal species that potentially could occur within the Lease Area and surrounding waters, along with their listing status under the *Endangered Species Act* (ESA), their relative likelihood of occurrence, and their documented abundance in the region. Additional details of species abundances are provided in Section 4 below in the individual species descriptions. The species in the region include six species of large baleen whale (mysticetes); 17 species of large and small toothed whales, dolphins, and porpoise (odontocetes); and three species of earless seals (phocid pinnipeds). It is unlikely that all 26 species would be present in the Lease Area during the site characterization survey because some of them are seasonal migrants and because their distributions vary among years based on factors such as oceanographic characteristics and prey availability. Seasonality and abundance reported in Table 4 and discussed below were mainly derived from the Northeast Large Pelagic Survey Collaborative (NLPSC) aerial surveys of the Rhode Island/Massachusetts Wind Energy Areas (RI/MA WEAs) during 2011–2015 (Kraus et al. 2016), Roberts et al. (2016, 2017, 2018) habitat-based density models, and the Kenney and Vigness-Raposa (2010) marine mammal assessment for the Rhode Island Ocean Special Area Management Plan as well as the NOAA Fisheries 2018 Stock Assessment Report (Hayes et al. 2019). Additional sighting data from Atlantic Marine Assessment Program for Protected Species (AMAPPS) shipboard and aerial surveys is also reported where relevant.

Of the 26 marine mammal species listed in Table 4, eleven species are considered to be “rare” in the area based on sighting and distribution data: blue whale (*Balaenoptera musculus*), dwarf and pygmy sperm whales (*Kogia sima* and *K. breviceps*), Cuvier's beaked whale (*Ziphius cavirostris*), four species of Mesoplodont beaked whales—Blainsville's (*Mesoplodon densirostris*), Gervais' (*M. europaeus*), Sowerby's (*M. bidens*), and True's (*M. mirus*)—Atlantic spotted dolphin (*Stenella frontalis*), striped dolphin (*Stenella coeruleoalba*), and harp seal (*Pagophilus groenlandicus*) (Hayes et al. 2019; Kenney and Vigness-Raposa 2010; Kraus et al. 2016; Roberts et al. 2016). Given the rarity of these species in the area and the relatively short duration of the proposed activities, the probability of these species being exposed to survey activities is quite low, and they are thus not considered further in this request. The short-finned pilot whale is also considered rare in this area; however, because the density and population estimates that

we use (Roberts et al. 2017) consider both long- and short-finned pilot whales together as a pilot whale "guild", our take request for pilot whales would include a small percentage of short-finned pilot whales.

Other marine mammal species that have been documented to occur within the U.S. Atlantic Exclusive Economic Zone (EEZ) but are not expected to be present in the Lease Area based on a scarcity of sightings and their known habitat preferences and distributions are: the West Indian manatee (*Trichechus manatus*), Bryde's whale (*Balaenoptera edeni*), beluga whale (*Delphinapterus leucas*), northern bottlenose whale (*Hyperoodon ampullatus*), killer whale (*Orcinus orca*), pygmy killer whale (*Feresa attenuata*), false killer whale (*Pseudorca crassidens*), melon-headed whale (*Peponocephala electra*), white-beaked dolphin (*Lagenorhynchus albirostris*), pantropical spotted dolphin (*Stenella attenuata*), Fraser's dolphin (*Lagenodelphis hosei*), rough-toothed dolphin (*Steno bredanensis*), clymene dolphin (*Stenella clymene*), spinner dolphin (*Stenella longirostris*), hooded seal (*Cystophora cristata*), and ringed seal (*Pusa hispida*) (CeTAP 1982; USFWS 2014; Hayes et al. 2019; Kenney and Vigness-Raposa, 2010; Kraus et al. 2016; Roberts et al. 2016). These 16 species are not considered further in this request.

Table 4. Marine mammal species that could be present in the BOEM OCS-A 0521 Renewable Energy Lease Area

Common Name (Species Name) and Stock	ESA/MMPA Status <sup>a</sup>	Hearing Group <sup>b</sup>	Occurrence in MA WEA <sup>c</sup>	Seasonality in MA WEA <sup>d</sup>	Abundance <sup>e</sup> (NOAA Fisheries best available)	Abundance <sup>f</sup> (Roberts et al. 2016, 2017, 2018)
<b>Mysticetes</b>						
Blue whale ( <i>Balaenoptera musculus</i> ) Western North Atlantic Stock	Endangered/ Strategic	Low-frequency cetacean	Rare	Mainly winter, but rare year-round	Unknown	11
Fin whale ( <i>Balaenoptera physalus</i> ) Western North Atlantic Stock	Endangered/ Strategic	Low-frequency cetacean	Common	Year-round, but mainly spring and summer	1,618	3,005
Humpback whale ( <i>Megaptera novaeangliae</i> ) Gulf of Maine Stock	Not Listed/Not Strategic	Low-frequency cetacean	Common	Year-round, but mainly spring and summer	896	248 Winter, 1,773 Summer
Minke whale ( <i>Balaenoptera acutorostrata</i> ) Canadian East Coast Stock	Not Listed/Not Strategic	Low-frequency cetacean	Common	Spring, summer, and fall (March to September)	2,591	652 Winter, 3,014 Summer
North Atlantic right whale ( <i>Eubalaena glacialis</i> ) Western North Atlantic Stock	Endangered/ Strategic	Low-frequency cetacean	Common	Winter and spring (December to May)	451	292 Winter, 394 Spring, 358 Summer, 124 Fall
Sei whale ( <i>Balaenoptera borealis</i> ) Nova Scotia Stock	Endangered/ Strategic	Low-frequency cetacean	Common	Spring and summer (March to June)	357	201 Winter, 453 Summer
<b>Odontocetes</b>						
Atlantic spotted dolphin ( <i>Stenella frontalis</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	Mid-frequency cetacean	Rare	NA	44,715	20,918 January, 22,787 April, 30,333 July, 24,325 October

Common Name (Species Name) and Stock	ESA/MMPA Status <sup>a</sup>	Hearing Group <sup>b</sup>	Occurrence in MA WEA <sup>c</sup>	Seasonality in MA WEA <sup>d</sup>	Abundance <sup>e</sup> (NOAA Fisheries best available)	Abundance <sup>f</sup> (Roberts et al. 2016, 2017, 2018)
Atlantic white-sided dolphin ( <i>Lagenorhynchus acutus</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	Mid-frequency cetacean	Common	Year-round	48,819	27,246 January, 35,909 April, 91,473 July, 77,042 October
Blainville's, Gervais', True's, and Sowerby's beaked whales ( <i>Mesoplodon densirostris</i> , <i>M. europaeus</i> , <i>M. mirus</i> , and <i>M. bidens</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	Mid-frequency cetacean	Rare	NA	7,092	5,937 <sup>g</sup>
Common bottlenose dolphin ( <i>Tursiops truncatus</i> ) Western North Atlantic Offshore Stock <sup>h</sup>	Not Listed/Not Strategic	Mid-frequency cetacean	Common	Year-round	77,532	69,251 January, 66,713 April, 75,620 July, 82,379 October
Cuvier's beaked whale ( <i>Ziphius cavirostris</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	Mid-frequency cetacean	Rare	NA	6,532	7,731
Dwarf and pygmy sperm whale ( <i>Kogia sima</i> and <i>K. breviceps</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	High-frequency cetacean	Rare	NA	3,785	6,197
Harbor porpoise ( <i>Phocoena phocoena</i> ) Gulf of Maine/Bay of Fundy Stock	Not Listed/Not Strategic	High-frequency cetacean	Common	Year-round, but less abundant in summer	79,883	13,782 Winter, 60,281 Summer
Pilot whale, long-finned ( <i>Globicephalus melas</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	Mid-frequency cetacean	Uncommon	Year-round	5,636	27,597 <sup>i</sup>
Pilot whale, short-finned ( <i>Globicephalus macrorhynchus</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	Mid-frequency cetacean	Rare	NA	28,924	27,597 <sup>i</sup>
Risso's dolphin ( <i>Grampus griseus</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	Mid-frequency cetacean	Uncommon	Year-round	18,250	5,254 January, 10,631 April, 23,010 July, 7,883 October

Common Name (Species Name) and Stock	ESA/MMPA Status <sup>a</sup>	Hearing Group <sup>b</sup>	Occurrence in MA WEA <sup>c</sup>	Seasonality in MA WEA <sup>d</sup>	Abundance <sup>e</sup> (NOAA Fisheries best available)	Abundance <sup>f</sup> (Roberts et al. 2016, 2017, 2018)
Short-beaked common dolphin ( <i>Delphinus delphis delphis</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	Mid-frequency cetacean	Common	Year-round, but more abundant in summer	70,184	76,792 January, 98,027 April, 121,292 July, 113,119 October
Sperm whale ( <i>Physeter macrocephalus</i> ) North Atlantic Stock	Endangered/Strategic	Mid-frequency cetacean	Uncommon	Mainly summer and fall	2,288	4,199 <sup>g</sup>
Striped dolphin ( <i>Stenella coeruleoalba</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	Mid-frequency cetacean	Rare	NA	54,807	76,660
<b>Pinnipeds</b>						
Gray seal ( <i>Halichoerus grypus</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	Phocid pinniped	Common	Year-round	27,131	10,709 January, 14,246 April, 11,961 July, 8,581 October <sup>k</sup>
Harbor seal ( <i>Phoca vitulina</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	Phocid pinniped	Common	Year-round, but rare in summer	75,834	10,709 January, 14,246 April, 11,961 July, 8,581 October <sup>k</sup>
Harp seal ( <i>Pagophilus groenlandicus</i> ) Western North Atlantic Stock	Not Listed/Not Strategic	Phocid pinniped	Uncommon	Winter and spring	Unknown <sup>l</sup>	10,709 January, 14,246 April, 11,961 July, 8,581 October <sup>k</sup>

<sup>a</sup> Listing status under the US Endangered Species Act (ESA) and Marine Mammal Protection Act (MMPA).

<sup>b</sup> Hearing group according to NOAA Fisheries technical guidance (NMFS 2018). NOTE: Hearing groups names were recently revised by Southall et al. (2019).

<sup>c</sup> Occurrence in the Massachusetts Wind Energy Area (MA WEA) is mainly derived from Hayes et al. (2019), Kenney and Vigness-Raposa (2010), Kraus et al. (2016), and Roberts et al. (2016).

<sup>d</sup> Seasonality in the MA WEA was mainly derived from Kraus et al. (2016) and Kenney and Vigness-Raposa (2010).

<sup>e</sup> "Best Available" population estimate is from NOAA Fisheries 2018 Stock Assessment Report (Hayes et al. 2019).

<sup>f</sup> Abundance estimates are from habitat-based density modeling of the Atlantic EEZ from Roberts et al. (2016, 2017, and 2018).

<sup>g</sup> The four Mesoplodont beaked whale species are grouped in Roberts et al. (2017).

- <sup>h</sup> Common bottlenose dolphins occurring in the MA Wind Energy Area likely belong to the Western North Atlantic Offshore Stock. It is possible that some could belong to the Western North Atlantic Northern Migratory Coastal Stock (listed as depleted under the MMPA), but the northernmost range of that stock is south of the Lease Area.
- <sup>i</sup> Long-finned and short-finned pilot whales are grouped in Roberts et al. (2017).
- <sup>j</sup> Roberts et al. (2017) sperm whale abundance estimate consists of 223 for the shelf area and 3,976 for the slope and abyss.
- <sup>k</sup> All phocid seals are considered together as a group in Roberts et al. (2018).
- <sup>l</sup> Hayes et al. (2019) report insufficient data to estimate the population size of harp seals in U.S. waters; however, the best estimate for the whole population is 7.4 million and this appears to be stable.

## 4.0 AFFECTED SPECIES STATUS AND DISTRIBUTION

As discussed in Section 3 above, fifteen species of marine mammals are known to occur either commonly or uncommonly (but with some regularity) within the Lease Area and surrounding waters. The North Atlantic right whale (NARW), fin whale, sei whale, and sperm whale are all considered endangered under the ESA. These four species are also all considered strategic stocks under the *Marine Mammal Protection Act* (MMPA; Hayes et al. 2019). The common bottlenose dolphins occurring in the Lease Area would likely belong to the Western North Atlantic Offshore Stock, which is not considered strategic. It is possible, however, that some could belong to the Western North Atlantic Northern Migratory Coastal Stock, which is considered depleted under the MMPA and therefore a strategic stock, but the northernmost range of that stock is generally south of the Lease Area. The sections below provide additional details on the distribution, abundance, and status of the marine mammal species or stocks that could occur in the Lease Area.

### 4.1. Cetaceans

#### 4.1.1. Fin Whale (*Balaenoptera physalus*)

The fin whale is the second largest baleen whale and is widely distributed in all the world's oceans, but is most abundant in temperate and cold waters (Aguilar and García-Vernet 2018). Fin whales are presumed to migrate seasonally between feeding and breeding grounds, but their migrations are less well defined than for other baleen whales. In the North Atlantic, some feeding areas have been identified but there are no known wintering areas (Aguilar and García-Vernet 2018). Fin whales are found in the summer from Baffin Bay, Spitsbergen, and the Barents Sea south to North Carolina and the coast of Portugal (Rice 1998). Apparently not all individuals migrate, because in winter they have been sighted from Newfoundland to the Gulf of Mexico and the Caribbean Sea, and from the Faroes and Norway south to the Canary Islands (Rice 1998). Fin whales off the eastern United States, Nova Scotia, and the southeastern coast of Newfoundland are believed to constitute a single stock under the present International Whaling Commission (IWC) management scheme (Donovan 1991), which has been called the Western North Atlantic stock.

#### Distribution

In the U.S. Atlantic EEZ, fin whales are the most commonly observed large whale, accounting for almost half of all large whales sighted over the continental shelf during aerial surveys from Cape Hatteras to Nova Scotia (CETAP 1982). Western North Atlantic fin whales typically feed in the Gulf of Maine and the waters surrounding New England, but mating and calving (and general wintering) areas are largely unknown (Hain et al. 1992; Hayes et al. 2019). It is likely that fin whales occurring in the U.S. Atlantic EEZ undergo migrations into Canadian waters, open-ocean areas, and perhaps even subtropical or tropical regions. Hain et al. (1992) suggest that calving takes place during October to January in latitudes of the US mid-Atlantic region.

Kraus et al. (2016) suggest that, compared to other baleen whale species, fin whales have a high multi-seasonal relative abundance in the Rhode Island/Massachusetts (RI/MA) and MA WEAs and surrounding areas. Fin whales were observed during spring and summer of the 2011–2015 NLPSC aerial survey. This species was observed primarily in the offshore (southern) regions of the RI/MA and MA WEAs during spring and was found closer to shore (northern areas) during the summer months (Kraus et al. 2016). Calves were observed three times and feeding was observed nine times during the Kraus et al. (2016) study. Although fin whales were largely absent from visual surveys in the RI/MA and MA WEAs in the fall and winter months (Kraus et al. 2016), acoustic data indicated that this species was present in the RI/MA and MA WEAs during all months of the year. Fin whales were acoustically detected in the MA WEA on 87%

of study days (889/1,020 days). Acoustic detection data indicated a lack of seasonal trends in Fin whale abundance with slightly less detections from April to July (Kraus et al. 2016). Because the detection range for fin whale vocalizations is more than 200 km, detected signals may have originated from areas far outside of the RI/MA and MA WEAs; however, arrival patterns of many fin whale vocalizations indicated that received signals likely originated from within the Kraus et al. (2016) study area. Fin whales were observed in the MA WEA and nearby waters during spring and summer of the 2010–2017 AMAPPS surveys (NEFSC and SEFSC 2011–2018).

### **Abundance**

Roberts et al. (2017) habitat-based density models provided abundance estimates of 1,629 fin whales in the U.S. Atlantic EEZ during February and 4,859 during June, which were the months predicted to have the lowest and highest abundances, respectively. The best available abundance estimate for the Western North Atlantic fin whale stock in U.S. waters from NMFS stock assessments is 1,618 individuals (Hayes et al. 2019).

### **Status**

The status of the Western North Atlantic stock of fin whales relative to its optimum sustainable population (OSP) in the U.S. Atlantic EEZ is unknown, but the North Atlantic population is listed as Endangered under the ESA and MA ESA, and NMFS considers this a strategic stock. There are currently no critical habitat areas established for the fin whale under the ESA. The Lease Area is flanked by two Biologically Important Areas (BIAs) for feeding for fin whales—the area to the northeast in the southern Gulf of Maine is considered a BIA year-round, while the area to the southwest off the tip of Long Island is a BIA from March to October (LaBrecque et al. 2015).

#### **4.1.2. Humpback Whale (*Megaptera novaeangliae*)**

Humpback whales are found in all ocean basins (Clapham 2018). This species is highly migratory, traveling between mid- to high-latitude waters where it feeds during spring through fall and lower latitude wintering grounds where it calves and generally does not feed. Routine migratory distances are thousands of kilometers (Kennedy et al. 2014). Although considered to be mainly a coastal species, humpback whales often traverse deep pelagic areas while migrating (Baker et al. 1998; Calambokidis et al. 2001; Garrigue et al. 2002). In the North Atlantic, six separate humpback whale sub-populations have been identified by their consistent maternally determined fidelity to different feeding areas (Clapham and Mayo 1987). These populations are found in the Gulf of Maine, Gulf of St. Lawrence, Newfoundland/Labrador, western Greenland, Iceland, and Norway (Hayes et al. 2019). The large majority of humpback whales that inhabit the waters in the U.S. Atlantic EEZ belong to the Gulf of Maine stock. In the western North Atlantic, the Gulf of Maine humpback whale stock is recognized as a distinct feeding stock on the basis of strong site fidelity by individual whales to the region and more recent genetic analysis (Palsbøll et al. 2001; Vigness-Raposa et al. 2010; Hayes et al. 2019).

### **Distribution**

Humpback whales in the Gulf of Maine stock typically feed in the waters between the Gulf of Maine and Newfoundland during spring, summer, and fall, but have been observed feeding in other areas, such as off the coast of New York (Sieswerda et al. 2015). Some humpback whales from the Gulf of Maine migrate to the West Indies in the winter, where they mate and calve their young (Katona and Beard 1990; Palsbøll et al. 1997). However, not all humpback whales from the Gulf of Maine stock migrate to the West Indies every winter because significant numbers of animals are observed in mid- and high-latitude regions at this time (Swingle et al. 1993).

Kraus et al. (2016) observed humpback whales in the RI/MA and MA WEAs and surrounding areas during all seasons of the 2011–2015 NLPSC aerial survey. Humpback whales were observed most often

during the spring and summer months, with a peak from April to June. Calves were observed 10 times and feeding was observed 10 times during the Kraus et al. (2016) study. That study also observed one instance of courtship behavior. Although humpback whales were only rarely seen during fall and winter surveys, acoustic data indicate that this species may be present within the MA WEA year-round, with the highest rates of acoustic detections in winter and spring (Kraus et al. 2016). Humpback whales were acoustically detected in the MA WEA on 56% of acoustic survey days (566/1,020 days). Acoustic detections do not differentiate between individuals, so detections on multiple days could be the same or different individuals. The mean detection range for humpback whales using passive acoustic monitoring (PAM) was 30–36 km, with a mean radius of 36 km for the PAM system. Kraus et al. (2016) estimated that 63% of acoustic detections of humpback whales represented whales within their study area. Humpback whales were observed in the MA WEA and nearby waters during the spring and summer of the 2010–2017 AMAPPS surveys (NEFSC and SEFSC 2011–2018).

## Abundance

The most recent ocean basin-wide estimate of the North Atlantic humpback whale population is 11,570 (Palsbøll et al. 1997). Roberts et al. (2017) habitat-based density models provide abundance estimates of 248 humpback whales in the U.S. Atlantic EEZ during the winter and 1,773 during the summer. The best available population estimate for the Gulf of Maine stock from NOAA Fisheries stock assessments is 896 individuals and this population appears to be increasing (Hayes et al. 2019).

## Status

The entire humpback whale species was previously listed as endangered under the ESA. However, in September 2016, NOAA Fisheries identified 14 Distinct Population Segments (DPSs) of humpback whales and revised the ESA listing for this species (81 FR 62260). Four DPSs were listed as endangered, one as threatened, and the remaining nine were deemed not warranted for listing. Humpback whales in the U.S. Atlantic EEZ belong to the West Indies DPS, which is considered not warranted for listing under the ESA (81 FR 62260). The state of Massachusetts lists the humpback whale as Endangered under the MA ESA. The Gulf of Maine stock of humpback whales is no longer considered depleted by NMFS because it does not coincide with any listed DPS. It is also not considered strategic by NMFS because the U.S. fishery-caused mortality and serious injury does not exceed the potential biological removal (PBR) for this stock. For the period 2012 through 2016, the minimum annual rate of human-caused mortality and serious injury to the Gulf of Maine humpback whale stock averaged 9.7 animals per year (Hayes et al. 2019).

Humpback whales in the Western North Atlantic have been experiencing an Unusual Mortality Event (UME) since January 2016 that appears to be related to a larger than usual number of vessel collisions (NOAA Fisheries 2019a). Of the whales examined, about half had evidence of human interaction (ship strike or entanglement). In total, 105 mortalities were documented through October 2, 2019, as part of this event, including 18 off Massachusetts (NOAA Fisheries, 2019a). A BIA for humpback whales for feeding has been designated northeast of the Lease Area in the Gulf of Maine, Stellwagen Bank, and the Great South Channel from March through December (LaBrecque et al. 2015).

### 4.1.3. Common Minke Whale (*Balaenoptera acutorostrata*)

Minke whales have a cosmopolitan distribution that spans ice-free latitudes (Stewart and Leatherwood 1985). They occur in both coastal and offshore waters (Perrin et al. 2018). Three species are recognized worldwide, with only the common Minke whale occurring in the northern hemisphere. Minke whales are generally observed alone or in small groups of two or three individuals; larger aggregations may occur at higher latitudes (Katona et al. 1993; Perrin et al. 2018). There are four recognized populations in the Atlantic Ocean (Donovan 1991). Minke whales found in the U.S. Atlantic EEZ are considered part of the Canadian East Coast stock, which inhabits the area from the western half of the Davis Strait (45°W) to the Gulf of Mexico (Hayes et al. 2019).

## Distribution

The Minke whale is common off the U.S. east coast over continental shelf waters, especially off New England during spring and summer (CETAP 1982). It is the third most abundant large whale in the EEZ. There is a seasonal component to their distribution in the Northwest Atlantic. This species is most abundant in New England waters during spring through fall while September through April they are most abundant in deep oceanic waters throughout the North Atlantic (Hayes et al. 2019).

Kraus et al. (2016) observed Minke whales in the RI/MA and MA WEAs and surrounding areas primarily from May to June during the 2011–2015 NLPSC aerial survey. This species demonstrated a distinct seasonal habitat usage pattern that was consistent throughout the study. Minke whales were not observed between October and February, but acoustic data indicate the presence of this species in the winter months. Calves were observed twice, and feeding was also observed twice during the Kraus et al. (2016) study. Minke whales were acoustically detected in the MA WEA on 28% of project days (291/1,020 days). Minke whale acoustic presence data also exhibited a distinct seasonal pattern; acoustic presence was lowest in the months of December and January, steadily increased beginning in February, peaked in April, and exhibited a gradual decrease throughout the summer months (Kraus et al. 2016). Acoustic detection range for this species was small enough that over 99% of detections were limited to within the Kraus et al. (2016) study area. Minke whales were observed several times in the MA WEA and nearby waters during spring and summer of the 2010–2017 AMAPPS surveys (NEFSC and SEFSC 2011–2018).

## Abundance

Roberts et al. (2017) habitat-based density models provide abundance estimates of 652 Minke whales in the U.S. Atlantic EEZ during winter (November–March) and 3,014 during summer (April–October) months. The best abundance estimate for the U.S. Atlantic EEZ from NOAA Fisheries stock assessments is 2,591 (Hayes et al. 2019). This estimate is likely biased low because it does not account for a number of Minke whales in Canadian waters and did not account for availability bias due to submerged animals.

## Status

Minke whales are not listed as threatened or endangered under the ESA and the Canadian East Coast Stock is not considered strategic under the MMPA. Minke whales in the Western North Atlantic have been experiencing a UME since January 2017 with some evidence of human interactions as well as infectious disease but more study is required (NOAA Fisheries 2019b). In total, 73 mortalities were documented through September 30, 2019 as part of this event, including 27 mortalities in Massachusetts (NOAA Fisheries 2019b). A BIA for Minke whales for feeding has been designated east of the Lease Area from March through November (LaBrecque et al. 2015).

### 4.1.4. North Atlantic Right Whale (*Eubalaena glacialis*)

NARWs are among the rarest of all marine mammal species in the Atlantic Ocean. Likely only about 450 individuals remain in the population, and after appearing to be recovering from a low of about 270 animals in 1990, this population now appears to be declining (Pace et al. 2017). NARWs are skim feeders, swimming slowly at or below the surface with mouth open to capture prey, which consists entirely of zooplankton (Kenney 2018). Research suggests that NARWs must locate and exploit extremely dense patches of zooplankton to feed efficiently (Mayo and Marx 1990). These dense zooplankton patches are a primary characteristic of the spring, summer, and fall NARW habitats (Kenney et al. 1986, 1995). NARWs are usually observed in groups of less than 12 individuals, and most often as single individuals or pairs. Larger groups may be observed in feeding or breeding areas (Jefferson et al. 2008). The NARW is a migratory species that travels from high-latitude feeding waters to low-latitude calving and breeding grounds.

## Distribution

The Western Atlantic stock of NARWs ranges primarily from calving grounds in coastal waters of the southeastern United States to feeding grounds in New England waters and the Canadian Bay of Fundy, Scotian Shelf, and Gulf of St. Lawrence (Hayes et al. 2019). These whales undertake a seasonal migration from their northeast feeding grounds (generally spring, summer, and fall habitats) south along the U.S. east coast to their calving grounds in the waters of the southeastern United States (Kenney and Vigness-Raposa 2010). However, this species has been observed feeding in winter in the mid-Atlantic region and has been recorded off the coast of New Jersey in all months of the year (Whitt et al. 2013). Surveys demonstrate the existence of seven areas where NARWs congregate seasonally: the coastal waters of the southeastern United States, the Great South Channel, Jordan Basin, Georges Basin along the northeastern edge of Georges Bank, Cape Cod and Massachusetts Bays, the Bay of Fundy, and the Roseway Basin on the Scotian Shelf (Hayes et al. 2019).

Kraus et al. (2016) observed NARWs in the RI/MA and MA WEAs and surrounding waters in winter and spring during the 2011–2015 NLPSC aerial survey and observed 11 instances of courtship behavior. The greatest sightings per unit effort (SPUE) in the RI/MA and MA WEAs was in March. Seventy-seven unique individual NARWs were observed in the RI/MA and MA WEAs over the duration of the NLPSC surveys (Kraus et al. 2016). No calves were observed. Kraus et al. (2016) acoustically detected NARWs with PAM within the MA WEA on 43% of project days (443/1,020 days) and during all months of the year. Acoustic detections do not differentiate between individuals, so detections on multiple days could be the same or different individuals. NARWs exhibited notable seasonal variability in acoustic presence, with maximum occurrence in the winter and spring (January through March), and minimum occurrence in summer (July, August, and September). The mean detection range for NARWs using PAM was 15–24 km, with a mean radius of 21 km for the PAM system within the study area.

Roberts et al. (2016) predict that the highest density of NARWs in the MA WEA and adjacent waters occurs in April, and Kraus et al. (2016) reported greatest levels of SPUE of NARWs in the WEA in March. The NLPSC aerial surveys report no sightings of NARWs for the months of May through October, and reported only four sightings in December across all survey years (Kraus et al. 2016). NARWs were observed in the MA WEA and nearby waters during the winter, spring, and summer of the 2010–2017 AMAPPS surveys (NEFSC and SEFSC 2011–2018). Sightings of this species in the Lease Area are possible though NARWs are generally distributed further north at the time of year when the proposed survey is scheduled to occur.

## Abundance

Roberts et al. (2017) habitat-based density models provide abundance estimates of 292 NARWs in the U.S. Atlantic EEZ during winter (December–March), 394 during spring (April–June), 358 during summer (July–September), and 124 during fall (October–November) months. The best estimate of the NARW population size according to the NARW Consortium is 451 (Pettis et al. 2017). This comes from the Pace et al. (2017) model, which also reported a 99.99% probability that the NARW population declined from 2010 to 2015. This estimate was adopted by NMFS as the best available in their 2018 draft stock assessments (NOAA Fisheries 2019d). This estimate does not consider that NARWs have been experiencing an UME since June 7, 2017, with 30 documented deaths as of September 30, 2019 (NOAA Fisheries 2019c). This unusual mortality event appears to be driven by entanglement in fishing gear (5 cases suspected or confirmed in the U.S. and 2 in Canada) and blunt force trauma associated with ship strikes (7 cases suspected or confirmed in Canada and 1 in the U.S.) mainly in the Gulf of St. Lawrence, Canada. Cause of death findings for the unusual mortality event are based on full necropsies conducted on 18 of the 30 dead NARWs and support human interactions (vessel strikes and rope entanglements) as the cause of death for the majority of the whales (Daoust et al. 2017; NOAA Fisheries 2019c).

## Status

The size of the Western Atlantic stock of NARWs is considered extremely low relative to its OSP in the U.S. Atlantic EEZ (Hayes et al. 2019). The Western Atlantic Stock of NARWs is classified as a strategic stock under the MMPA and is listed as Endangered under the ESA and MA ESA. Historically, the population suffered severely from commercial overharvesting and has more recently been threatened by incidental fishery entanglement and vessel collisions (Knowlton and Kraus 2001; Kraus et al. 2005; Pace et al. 2017).

To protect this species from ship strikes, NOAA Fisheries designated Seasonal Management Areas (SMAs) in U.S. waters in 2008 (73 FR 60173). All vessels greater than 65 ft in overall length must operate at speeds of 10 knots or less within these areas during specific time periods. The Block Island Sound SMA overlaps with the southern portion of the MA WEA and is active between November 1 and April 30 each year. The Great South Channel SMA lies to the Northeast of the MA WEA and is active April 1 to July 31. In addition, the rule provides for the establishment of Dynamic Management Areas (DMAs) when and where NARWs are sighted outside SMAs. DMAs are generally in effect for two weeks and the 10 knots or less speed restriction is voluntary.

NOAA Fisheries has designated two critical habitat areas for the NARW under the ESA: the Gulf of Maine/Georges Bank region and the southeast calving grounds from North Carolina to Florida (81 FR 4837). Two additional critical habitat areas in Canadian waters, Grand Manan Basin and Roseway Basin, were identified in Canada's final recovery strategy for the NARW (Brown et al. 2009).

The Lease Area is encompassed by a NARW BIA for migration from March to April and from November to December (LaBrecque et al. 2015). The NARW BIA for migration includes the RI/MA and MA WEAs and beyond to the continental slope, extending northward to offshore of Provincetown, MA and southward to halfway down the Florida coast (LaBrecque et al. 2015). However, the proposed survey is scheduled to occur from April through September, which is outside the timing of this BIA.

### 4.1.5. Sei Whale (*Balaenoptera borealis*)

The sei whale occurs worldwide, with a preference for oceanic waters (Horwood 2018). It is uncommon in shelf waters. Sei whales undertake extensive seasonal migrations, feeding at subpolar latitudes during the summer and calving at lower latitudes in the winter. Sei whales often travel alone while migrating, but on feeding grounds they can be observed alone or in aggregations of 20-100 animals (Horwood 2018). Two stocks of sei whales are recognized in the western North Atlantic: the Labrador Sea Stock and the Nova Scotia Stock. Sei whales occurring within the Lease Area are considered part of the Nova Scotia stock, which includes continental shelf waters from the northeastern United States to areas south of Newfoundland (Hayes et al. 2017). The southern portions of the Nova Scotia stock's range includes the Gulf of Maine and Georges Bank during spring and summer (Hayes et al. 2017).

## Distribution

Sighting data suggest sei whale distribution is largely centered in the waters of New England and eastern Canada (Hayes et al. 2017; Roberts et al. 2016). There appears to be a strong seasonal component to sei whale distribution in U.S. waters. They are relatively widespread and most abundant in New England waters from spring to fall (April to July). During winter, the species is predicted to be largely absent (Roberts et al. 2016).

Kraus et al. (2016) observed sei whales in the RI/MA and MA WEAs and surrounding areas only between the months of March and June during the 2011–2015 NLPSC aerial survey. The number of sei whale observations was less than half that of other baleen whale species in the two seasons in which sei whales were observed (spring and summer). This species demonstrated a distinct seasonal habitat use pattern that was consistent throughout the study. Calves were observed three times and feeding was observed four times during the Kraus et al. (2016) study. Sei whales were not observed in the MA WEA

and nearby waters during the 2010–2017 AMAPPS surveys (NEFSC and SEFSC 2011–2018). However, there were observations during the 2016 and 2017 summer surveys that were identified as being either a fin or sei whale. Sei whales are expected to be present in the Lease Area and surrounding waters but much less common than the other baleen whale species.

### **Abundance**

Roberts et al. (2017) habitat-based density models provide abundance estimates of 201 sei whales in the U.S. Atlantic EEZ during winter (October–March) and 453 during summer (April–September). The best available abundance estimate for the Nova Scotia stock of sei whales from NMFS stock assessments is 357 individuals. This estimate is considered an underestimate because the full known range of the stock was not surveyed, the estimate did not include availability-bias correction for submerged animals, and there was uncertainty regarding population structure (Hayes et al. 2017).

### **Status**

Sei whales are listed as Endangered under the ESA and MA ESA and the Nova Scotia stock is considered strategic by NMFS. There are no critical habitat areas designated for the sei whale under the ESA. A BIA for feeding for sei whales occurs east of the Lease Area from May through November (LaBrecque et al. 2015).

#### **4.1.6. Atlantic White-Sided Dolphin (*Lagenorhynchus acutus*)**

Atlantic white-sided dolphins occur in cold temperate to subpolar waters of the North Atlantic in deep continental shelf and slope waters (Jefferson et al. 2008). They are often found concentrated in areas with high seafloor relief (Reeves et al. 2002). Though often found in shelf and slope waters, they can also be seen in coastal as well as deep oceanic waters (Cipriano 2018). Groups sizes can range from a few individuals to several hundred individuals. They can be seen feeding with large baleen whales or associating with other dolphin species (Cipriano 2018). The Western North Atlantic stock of Atlantic white-sided dolphins may consist of three separate populations: Gulf of Maine, Gulf of St. Lawrence, and Labrador Sea (Hayes et al. 2019). Animals observed off the eastern U.S. coast are part of the Gulf of Maine population, which is suggested as being separate from the nearby Gulf of St. Lawrence population based on distribution patterns and genetic analyses, but further research is necessary to support this.

### **Distribution**

Within the U.S. Atlantic EEZ, the Gulf of Maine population of white-sided dolphins occurs from about 39°N to Georges Bank as well as in the Gulf of Maine and Lower Bay of Fundy (Hayes et al. 2019). Sighting data indicate seasonal shifts in distribution (Northridge et al. 1997). From January to May, they are found in low numbers from Georges Bank to Jeffreys Ledge off New Hampshire. During June to September, they occur in large numbers from Georges Bank to the lower Bay of Fundy. In October through December, they occur at intermediate densities from southern Georges Bank to the southern Gulf of Maine (Payne and Heinemann 1990).

Kraus et al. (2016) suggest that Atlantic white-sided dolphins occur infrequently in the RI/MA and MA WEAs and surrounding areas. Effort-weighted average sighting rates for Atlantic white-sided dolphins could not be calculated because this species was only observed on eight occasions throughout the duration of the study (October 2011 through June 2015). No Atlantic white-sided dolphins were observed during the winter months, and this species was only sighted twice in the fall and three times in the spring and summer. It is possible that the NLPSC survey may have underestimated the abundance of Atlantic white-sided dolphins because this survey was designed to target large cetaceans and the majority of small cetaceans were not identified to species. Atlantic white-sided dolphins were seen during the spring and summer in the MA WEA and nearby waters during the 2010–2017 AMAPPS surveys (NEFSC and SEFSC 2011–2018).

## Abundance

Roberts et al. (2018) habitat-based density models provide abundance estimates of 91,473 Atlantic white-sided dolphins in the U.S. Atlantic EEZ during July and 77,042 during October, months that coincide with the proposed survey activities. According to NMFS, the best available abundance estimate for the Western North Atlantic stock of Atlantic white-sided dolphins is 48,819 individuals, estimated from data collected during a 2011 summer survey, but this estimate only covers the Gulf of Maine population not the entire western North Atlantic stock (Hayes et al. 2019).

## Status

The Atlantic white-sided dolphin is not listed as threatened or endangered under the ESA and the Western North Atlantic stock of Atlantic white-sided dolphins is not classified as strategic.

### 4.1.7. Common Bottlenose Dolphin (*Tursiops truncatus*)

Bottlenose dolphins are one of the most well-known and widely distributed species of marine mammal, found in most warm temperate and tropical seas in coastal as well as offshore waters (Wells and Scott 2018). They are commonly found in groups of two to 15 individuals, though aggregations of more than 1,000 individuals have been reported. They are considered generalist feeders and consume a wide variety of organisms, including fish, squid, and shrimp and other crustaceans (Jefferson et al. 2008).

## Distribution

The common bottlenose dolphin is a cosmopolitan species that occurs in temperate and tropical waters worldwide. Two distinct morphotypes of bottlenose dolphin, coastal and offshore, occur along the eastern coast of the United States (Curry and Smith 1997; Hersh and Duffield 1990; Mead and Potter 1995; Rosel et al. 2009). The offshore morphotype inhabits outer continental slope and shelf edge regions from Georges Bank to the Florida Keys, and the coastal morphotype is continuously distributed along the Atlantic Coast from south of New York to the Florida Peninsula (Hayes et al. 2017). Offshore common bottlenose dolphin sightings occur from Cape Hatteras to the eastern end of Georges Bank (Kenney 1990). There are 17 coastal, offshore, bay, and estuarine stocks of common bottlenose dolphins in the U.S. Atlantic EEZ. Bottlenose dolphins encountered in the Lease Area would likely belong to the Western North Atlantic Offshore Stock (Hayes et al. 2018). However, it is possible that a few animals could be from the North Atlantic Northern Migratory Coastal Stock, but they generally do not range farther north than New Jersey.

Kraus et al. (2016) observed common bottlenose dolphins during all seasons within the RI/MA and MA WEAs in the 2011–2015 NLPSC aerial survey. This was the second most commonly observed small cetacean species and exhibited little seasonal variability in abundance. One sighting of common bottlenose dolphins in the Kraus et al. (2016) study included calves, and one sighting involved mating behavior. It is possible that the NLPSC survey may have underestimated the abundance of common bottlenose dolphins because this survey was designed to target large cetaceans and the majority of small cetaceans were not identified to species (Kraus et al. 2016). Common bottlenose dolphins were observed in the MA WEA and nearby waters during spring, summer, and fall of the 2010–2017 AMAPPS surveys (NEFSC and SEFSC 2011–2018).

## Abundance

Roberts et al. (2018) habitat-based density models provide abundance estimates of 75,620 common bottlenose dolphins in the U.S. Atlantic EEZ during July and 82,379 during October, months that coincide with the proposed survey activities. The best available population estimate for the Western North Atlantic Offshore stock of bottlenose dolphins is 77,532 (Hayes et al. 2017). This estimate is from summer 2011 surveys covering waters from central Florida to the lower Bay of Fundy (Hayes et al. 2017). The best available estimate for the North Atlantic Northern Migratory Coastal Stock is 6,639 (Hayes et al. 2018).

## Status

Common bottlenose dolphins of the western North Atlantic are not listed as threatened or endangered under the ESA. The Western North Atlantic Offshore Stock is not considered strategic (Hayes et al. 2017). However, the western North Atlantic Northern Migratory Coastal stock of common bottlenose dolphins is considered strategic by NOAA Fisheries because it is listed as depleted under the MMPA (Hayes et al. 2018).

### 4.1.8. Harbor Porpoise (*Phocoena phocoena*)

The harbor porpoise inhabits cool temperate to subarctic waters of the Northern Hemisphere, generally within shallow coastal waters of the continental shelf but occasionally traveling over deeper, offshore waters (Jefferson et al. 2008). They are usually seen in small groups of one to three; occasionally they form much larger groups (Bjørge and Tolley 2018). There are likely four populations in the western North Atlantic: Gulf of Maine/Bay of Fundy, Gulf of St. Lawrence, Newfoundland, and Greenland (Gaskin 1984, 1992; Hayes et al. 2019). Individuals found in the Lease Area would be almost exclusively from the Gulf of Maine/Bay of Fundy stock.

## Distribution

During summer (July through September), harbor porpoises from the Gulf of Maine/Bay of Fundy stock are concentrated along the continental shelf within the northern Gulf of Maine and southern Bay of Fundy region (Hayes et al. 2019). During fall (October through December) and spring (April through June), they are more widely dispersed from New Jersey to Maine. During winter (January through March), they range from New Brunswick, Canada, to North Carolina (Hayes et al. 2019).

Kraus et al. (2016) indicate that harbor porpoises occur within the RI/MA and MA WEAs in fall, winter, and spring. Harbor porpoises were observed in groups ranging in size from three to 15 individuals and were primarily observed in the Kraus et al. (2016) study area from November through May, with very few sightings during June through September. It is possible that the NLPSC survey may have underestimated the abundance of harbor porpoise because this survey was designed to target large cetaceans and the majority of small cetaceans were not identified to species (Kraus et al. 2016). Harbor porpoises were observed in the MA WEA and nearby waters during spring and fall of the 2010–2017 AMAPPS surveys (NEFSC and SEFSC, 2011–2018).

## Abundance

Roberts et al. (2017) habitat-based density models provide an abundance estimate of 13,782 harbor porpoise in the U.S. Atlantic EEZ during winter (October to May) and 60,281 during summer (June to September) months. According to NMFS, the best abundance estimate of the Gulf of Maine/Bay of Fundy stock of harbor porpoise is 79,883 individuals, based on data collected during a 2011 line-transect survey, but this estimate is likely biased low because it did not cover the entire area of the stock's habitat and did not account for availability bias due to submerged animals (Hayes et al. 2019).

## Status

The harbor porpoise is not listed as threatened or endangered under the ESA and is not listed under the MA ESA. The Gulf of Maine/Bay of Fundy Stock of harbor porpoises is not considered strategic.

### 4.1.9. Pilot Whales (*Globicephala* spp.)

Two species of pilot whale occur within the Western North Atlantic: the long-finned pilot whale and the short-finned pilot whale. In general, short-finned pilot whales tend to have a tropical and subtropical distribution whereas long-finned pilot whales prefer colder temperate waters (Olson 2018). The two species are difficult to differentiate at sea and cannot be reliably distinguished during most surveys (Hayes et al.

2019; Rone et al. 2012), so abundance and density estimates are often calculated for the two species combined (e.g. Roberts et al. 2017). Pilot whales are wide-ranging and globally abundant, and form large schools averaging 20-90 individuals comprised of socially stable pods of 10-20 whales (Olson 2018). They are often seen in mixed-species aggregations with common bottlenose dolphins and sometimes with other whale species. The two pilot whale species within the U.S. Atlantic EEZ are categorized into Western North Atlantic stocks.

### **Distribution**

In U.S. Atlantic waters, pilot whales are distributed principally along the continental shelf edge off the northeastern U.S. coast in winter and early spring (CETAP 1982; Abend and Smith 1999; Hamazaki 2002; Payne and Heinemann 1993). In late spring, pilot whales move onto Georges Bank, into the Gulf of Maine, and into more northern waters, where they remain through late fall (CeTAP 1982; Payne and Heinemann 1993). Long-finned and short-finned pilot whales overlap spatially along the mid-Atlantic shelf break between New Jersey and the southern flank of Georges Bank (Hayes et al. 2019; Payne and Heinemann 1993). Long-finned pilot whales have occasionally been observed stranded as far south as South Carolina, and short-finned pilot whale have stranded as far north as Massachusetts (Hayes et al. 2019). The latitudinal ranges of the two species therefore remain uncertain. However, south of Cape Hatteras, most pilot whale sightings are expected to be short-finned pilot whales, while north of approximately 42°N, most pilot whale sightings are expected to be long-finned pilot whales (Hayes et al. 2019). Based on the distributions described in Hayes et al. (2019), pilot whale sightings in the Lease Area would most likely be long-finned pilot whales.

Kraus et al. (2016) observed pilot whales infrequently in the RI/MA and MA WEAs and surrounding areas during the 2011–2015 NLPSC aerial survey. Effort-weighted average sighting rates for pilot whales could not be calculated. No pilot whales were observed during the fall or winter, and these species were only observed 11 times in the spring and three times in the summer. Two of these sightings included calves. It is possible that the NLPSC survey may have underestimated the abundance of pilot whales, as this survey was designed to target large cetaceans and most small cetaceans were not identified to species (Kraus et al. 2016). No pilot whales were observed in the MA WEA and nearby waters during the 2010–2017 AMAPPS surveys from 2010–2017 (NEFSC and SEFSC 2011–2018).

### **Abundance**

Roberts et al. (2017) habitat-based density models provide an abundance estimate of 27,597 pilot whales in the U.S. Atlantic EEZ. This estimate includes both long-finned and short-finned pilot whales. According to NMFS, the best available population estimate for long-finned pilot whales in the U.S. Atlantic EEZ is 5,636, from summer 2011 surveys from central Virginia to the lower Bay of Fundy. For short-finned pilot whales, the best available estimate is 28,924 from summer 2016 surveys from central Florida to Georges Bank because those surveys covered the full range of this species in U.S. Atlantic waters (Hayes et al. 2019).

### **Status**

Total annual estimated average fishery-related mortality or serious injury during 2012–2016 was 27 for long-finned pilot whales (Hayes et al. 2019). Total annual human-caused mortality for short-finned pilot whales during this period is unknown, but the mean annual fishing mortality due to pelagic longline fishing was estimated at 168 (Hayes et al. 2019). Neither pilot whale species is listed as threatened or endangered under the ESA and neither stock is considered strategic under the MMPA (Hayes et al. 2019).

#### **4.1.10. Risso's Dolphin (*Grampus griseus*)**

Risso's dolphins are located worldwide in both tropical and temperate waters (Jefferson et al. 2008; Jefferson et al. 2014). This species apparently prefers steep sections of the continental shelf edge and deep

offshore waters 100–1000 m deep (Hartman 2018). They are known to frequent seamounts and escarpments (Kruse et al. 1999). Risso's dolphins are deep divers, feeding primarily on deep mesopelagic cephalopods such as squid, octopus, and cuttlefish and likely forage at night (Hartman 2018). This species has been seen associating with other delphinid species. Risso's dolphins in the U.S. Atlantic EEZ are part of the Western North Atlantic stock (Hayes et al. 2019).

### **Distribution**

The Western North Atlantic stock of Risso's dolphins inhabits waters from Florida to eastern Newfoundland (Baird and Stacey 1991; Leatherwood et al. 1976). During spring, summer, and fall, Risso's dolphins are distributed along the continental shelf edge from Cape Hatteras northward to Georges Bank (CeTAP 1982; Payne et al. 1984). During the winter, the distribution extends outward into oceanic waters (Payne et al. 1984).

Kraus et al. (2016) results from the 2011–2015 NLPSC aerial survey suggest that Risso's dolphins occur infrequently in the RI/MA and MA WEAs and surrounding areas. Effort-weighted average sighting rates for Risso's dolphins could not be calculated. No Risso's dolphins were observed during summer, fall, or winter, and this species was only observed twice in the spring. It is possible that the NLPSC survey may have underestimated the abundance of Risso's dolphins, as this survey was designed to target large cetaceans and the majority of small cetaceans were not identified to species. Risso's dolphins were observed in the MA WEA and nearby waters during spring and summer of the 2010–2017 AMAPPS surveys (NEFSC and SEFSC 2011–2018).

### **Abundance**

Roberts et al. (2018) habitat-based density models provide abundance estimates of 10,631 Risso's dolphins in the U.S. Atlantic EEZ during April, 23,010 during July, and 7,883 during October, months that coincide with the proposed survey activities. The best available abundance estimate for Risso's dolphins in the Western North Atlantic stock from NOAA Fisheries stock assessments is 18,250, estimated from data collected during 2011 surveys, and is biased low because it is not corrected for availability bias due to submerged animals (Hayes et al. 2019).

### **Status**

Risso's dolphins are not listed as threatened or endangered under the ESA and the Western North Atlantic stock is not considered strategic.

#### **4.1.11. Short-beaked Common Dolphin (*Delphinus delphis delphis*)**

The common dolphin is one of the most abundant and widely distributed cetaceans, occurring in warm temperate and tropical regions worldwide from about 60°N to 50°S (Perrin 2018). These dolphins occur in schools of hundreds or thousands of individuals and often associate with pilot whales or other dolphin species (Perrin 2018). Until very recently, short-beaked and long-beaked common dolphins were thought to be separate species but evidence now suggests that this character distinction is based on ecology rather than genetics (Perrin 2018). A single species with three subspecies of common dolphin are recognized by the Society for Marine Mammalogy Committee on Taxonomy (Committee on Taxonomy 2018). The common dolphins occurring in the Lease Area would belong to the subspecies *Delphinus delphis delphis* and be of the short-beaked variety (Perrin 2018). Short-beaked common dolphins in the U.S. Atlantic EEZ belong to the Western North Atlantic stock (Hayes et al. 2018).

### **Distribution**

Within the U.S. Atlantic EEZ, short-beaked common dolphins general occur from Cape Hatteras, North Carolina to the Scotian Shelf (Hayes et al. 2019). This species is highly seasonal and migratory. In

the U.S. Atlantic EEZ, they are distributed along the continental shelf between the 100- and 2,000-m isobaths (328–6,561.6 ft) and are associated with Gulf Stream features (CeTAP 1982; Hamazaki 2002; Hayes et al. 2019; Selzer and Payne 1988). Short-beaked common dolphins occur from Cape Hatteras northeast to Georges Bank (35° to 42°N) during mid-January to May and move as far north as the Scotian Shelf from mid-summer to fall (Selzer and Payne 1988).

Kraus et al. (2016) suggested that short-beaked common dolphins occur year-round in the RI/MA and MA WEAs and surrounding areas based on data from the 2011–2015 NLPSC aerial survey. They were the most frequently observed small cetacean species within the Kraus et al. (2016) study area. Short-beaked common dolphins were observed in the RI/MA and MA WEAs in all seasons but were most frequently observed during the summer months; observations of this species peaked between June and August. Two sightings of short-beaked common dolphins in the Kraus et al. (2016) study included calves, two sightings involved feeding behavior, and three sightings involved mating behavior. Sighting data indicate that short-beaked common dolphin distribution tended to be farther offshore during the winter months than during spring, summer, and fall. It is possible that the NLPSC survey may have underestimated the abundance of short-beaked common dolphins, because this survey was designed to target large cetaceans and the majority of small cetaceans were not identified to species (Kraus et al. 2016). Short-beaked common dolphins were observed in the MA WEA and nearby waters during all seasons of the 2010–2017 AMAPPS surveys (NEFSC and SEFSC 2011–2018).

### **Abundance**

Roberts et al. (2018) habitat-based density models provide abundance estimates of 121,292 short-beaked common dolphins in the U.S. Atlantic EEZ during July and 113,119 during October, months that coincide with the proposed survey activities. According to NOAA Fisheries, the best available population estimate in the U.S. Atlantic EEZ for the Western North Atlantic short-beaked common dolphin stock is 70,184, based on shipboard and aerial surveys from 2011 (Hayes et al. 2019).

### **Status**

The short-beaked common dolphin is not listed as threatened or endangered under the ESA and the Western North Atlantic Stock of short-beaked common dolphins is not considered strategic.

#### **4.1.12. Sperm Whale (*Physeter macrocephalus*)**

The sperm whale is the largest of the toothed whales, with males reaching lengths of 16 m and the much smaller females reaching lengths of 11 m (Whitehead 2018). This species is widely distributed, occurring from the edge of the polar pack ice to the equator in both hemispheres (Whitehead 2018). In general, they are distributed over large temperate and tropical areas that have high secondary productivity and steep underwater topography, such as volcanic islands (Jacquet and Whitehead 1996). Their distribution and relative abundance can vary in response to prey availability, most notably squid (Jacquet and Gendron 2002). This species can remain submerged for over an hour and dive to depths as great as 1,000 m. Sperm whales form stable social groups and exhibit a geographic social structure—females and juveniles form mixed groups and primarily reside in tropical and subtropical waters whereas males are more solitary and wide-ranging and occur at higher latitudes (Whitehead 2002, 2003). A single stock of sperm whales is recognized for the North Atlantic, and Reeves and Whitehead (1997) and Dufault et al. (1999) suggest that sperm whale populations lack clear geographic structure.

### **Distribution**

Though sperm whales mainly reside in deep-water habitats along the shelf edge and in mid-ocean regions, this species has been observed in relatively high numbers in the shallow continental shelf areas of southern New England (Scott and Sadove 1997). In the U.S. Atlantic EEZ waters, sperm whales appear to exhibit seasonal movement patterns (CETAP 1982; Scott and Sadove 1997). During the winter, they are

concentrated to the east and north of Cape Hatteras. This distribution shifts northward in spring, when sperm whales are most abundant in the central portion of the mid-Atlantic bight to the southern region of Georges Bank. In summer, this distribution continues to move northward, including the area east and north of Georges Bank and the continental shelf to the south of New England. In fall months, sperm whales are most abundant on the continental shelf to the south of New England and remain abundant along the continental shelf edge in the mid-Atlantic bight.

Kraus et al. (2016) observed sperm whales four times in the RI/MA and MA WEAs and surrounding areas in the summer and fall during the 2011–2015 NLPSC aerial survey. Sperm whales, traveling singly or in groups of three or four, were observed three times in August and September of 2012, and once in June of 2015. Effort-weighted average sighting rates could not be calculated. The frequency of sperm whale clicks exceeded the maximum frequency of PAM equipment used in the Kraus et al. (2016) study, so no acoustic data are available for this species from that study. Sperm whales were observed only once in the MA WEA and nearby waters during the 2010–2017 AMAPPS surveys (NEFSC and SEFSC 2011–2018). This occurred during a summer shipboard survey in 2016.

## Abundance

Roberts et al. (2017) habitat-based density models provide an abundance estimate of 4,199 sperm whales in the U.S. Atlantic EEZ. That estimate includes 223 animals in shelf waters and 3,976 in slope and abyssal waters. The most recent best available population estimate for the U.S. Atlantic EEZ from NMFS stock assessments is 2,288 (Waring et al. 2015). This estimate was generated from the sum of surveys conducted in 2011, and is likely an underestimate of total abundance, because these surveys were not corrected for sperm whale dive time.

## Status

Sperm whales are listed as Endangered under the ESA and MA ESA, and the North Atlantic stock is considered strategic by NMFS. There are no critical habitat areas designated for the sperm whale under the ESA.

## 4.2. Pinnipeds

Three species of pinnipeds occur in the Atlantic Ocean near the Lease Area: the harbor seal, gray seal, and harp seal. All three pinniped species are more likely to occur in the region during winter and early spring, but could be seen at other times of the year.

### 4.2.1. Gray Seal (*Halichoerus grypus*)

Gray seals are found throughout the temperate and subarctic waters of the North Atlantic (King 1983). In the northwestern Atlantic, they occur from Labrador south to Massachusetts (King 1983). Gray seals are the second most common pinniped in the U.S. Atlantic EEZ (Jefferson et al. 2008). This species inhabits temperate and sub-arctic waters and lives on remote, exposed islands, shoals, and unstable sandbars (Jefferson et al. 2008). These seals are generally gregarious and live in loose colonies while breeding (Jefferson et al. 2008). Though they spend most of their time in coastal waters, gray seals can dive to depths of 300 m (984 ft), and frequently forage on the OCS (Jefferson et al. 2008; Lesage and Hammill 2001). Gray seals form three populations in the Atlantic (Katona et al. 1993). Individuals occurring in the Lease Area belong to the Northwest Atlantic population, which is equivalent to the western North Atlantic stock (Hayes et al. 2019).

## Distribution

The Northwest Atlantic population of gray seals ranges from New Jersey to Labrador (Hayes et al. 2019). There are three breeding concentrations in eastern Canada: Sable Island, the Gulf of St. Lawrence,

and along the east coast of Nova Scotia (Lavigne and Hammill 1993). In U.S. waters, gray seals currently pup at four established colonies from late December to mid-February: Muskeget and Monomoy Islands in Massachusetts, and Green and Seal Islands in Maine (Hayes et al. 2019). Pupping was also observed in the early 1980s on small islands in Nantucket-Vineyard Sound and since 2010 at Nomans Island in Massachusetts (Hayes et al. 2019). The distributions of individuals from different breeding colonies overlap outside the breeding season. Gray seals could be present year-round in the Lease Area (Hayes et al. 2019).

Kraus et al. (2016) observed gray seals in the RI/MA and MA WEAs and surrounding areas during the 2011–2015 NLPSC aerial survey, but this survey was designed to target large cetaceans so locations and numbers of seal observations were not included in the study report. Gray seals were regularly observed in the MA WEA and nearby waters during all seasons of the 2010–2017 AMAPPS surveys (NEFSC and SEFSC 2011–2018). Gray seals tagged near Cape Cod during Phase I of AMAPPS showed strong site fidelity to Cape Cod throughout the summer and fall then movement south and east toward Nantucket beginning in mid-December (Palka et al. 2017). One pup tagged in January spent most of the month that the tag was active in the MA WEA.

### **Abundance**

There are no current estimates of the Northwest Atlantic gray seal population, but estimates are available for portions of the stock for certain time periods (Hayes et al. 2019). The total population of gray seals in Canada was estimated at 424,300 for 2016 (DFO 2017). For U.S. waters, NOAA Fisheries best estimate of the population is 27,131 (Hayes et al. (2019). Moxley et al. (2017) used Google Earth imagery to provide an estimate of between 30,000 and 50,000 gray seals in southeast Massachusetts from haulout sites on Cape Cod, Nantucket, Martha's Vineyard, and smaller islands, sandbars, and shoals in the area. Roberts et al. (2018) provide abundance estimates of 11,961 for July and 8,581 for October for all phocid seals, which are primarily harbor and gray seals, in the U.S. Atlantic EEZ.

### **Status**

Gray seals are not considered strategic under the MMPA, are not listed as threatened or endangered under the ESA, and are not listed under the MA ESA. Gray seals have been experiencing a UME since July of 2018, with elevated mortalities across Maine, New Hampshire, and Massachusetts (NOAA Fisheries, 2019d). There were 2,954 seal strandings (primarily harbor and gray seals, but also some harp and hooded seals) between July 1, 2018 and September 25, 2019 with 914 strandings in Massachusetts. Evidence so far suggests phocine distemper virus as the cause of the strandings.

#### **4.2.2. Harbor Seal (*Phoca vitulina vitulina*)**

The harbor seal has a wide distribution throughout coastal waters between 30°N and ~80°N (Teilmann and Galatius 2018). It is the most common pinniped in the U.S. Atlantic EEZ (Katona et al. 1993). Harbor seals usually occur in coastal waters, commonly in bays, estuaries, and rivers. Most harbor seals haul out on land daily, although they can spend several days at sea feeding (Jefferson et al. 2008). Harbor seals complete both shallow and deep dives during hunting, depending on the availability of prey (Tollit et al. 1997). Although the stock structure of the Western North Atlantic population is unknown, it is thought that harbor seals found along the eastern U.S. and Canadian coasts represent one population that is termed the Western North Atlantic Stock (Andersen and Olsen 2010; Temte and Wiig 1991).

### **Distribution**

In the western Atlantic, harbor seal distribution ranges from the eastern Canadian Arctic and Greenland south to New Jersey (Teilmann and Galatius 2018). Harbor seals are year-round inhabitants of the coastal waters of eastern Canada and Maine and they occur seasonally along the southern New England to New Jersey coasts from September through late May (Barlas 1999; Katona et al. 1993; Schneider and Payne 1983; Schroeder 2000). A northward movement from southern New England to Maine and eastern

Canada occurs prior to the pupping season, which takes place from mid-May through June along the Maine coast (Kenney 1994; Richardson 1976; Whitman and Payne 1990; Wilson 1978). Harbor seals are generally present in the Lease Area seasonally, from September through May (Hayes et al. 2019).

Kraus et al. (2016) observed harbor seals in the RI/MA and MA WEAs and surrounding areas during the 2011–2015 NLPSC aerial survey, but this survey was designed to target large cetaceans so locations and numbers of seal observations were not included in the study report. Harbor seals have five major haul-out sites in and near the RI/MA and MA WEAs: Monomoy Island, the northwestern side of Nantucket Island, Nomans Land, the north side of Gosnold Island, and the southeastern side of Naushon Island (Payne and Selzer 1989). Payne and Selzer (1989) conducted aerial surveys and found that for haul-out sites in Massachusetts and New Hampshire, Monomoy Island had approximately twice as many seals as any of the 13 other sites in the study (maximum count of 1,672 in March of 1986). Harbor seals were observed in the MA WEA and nearby waters during spring, summer, and fall of the 2010–2017 AMAPPS surveys (NEFSC and SEFSC 2011–2018).

### **Abundance**

The best estimate of abundance for harbor Seals in the Western North Atlantic Stock is 75,834 (Hayes et al. 2019). This estimate was derived from a coast-wide survey along the Maine coast during May and June 2012. Roberts et al. (2018) provide abundance estimates of 11,961 for July and 8,581 for October for all phocid seals, which are primarily harbor and gray seals, in the U.S. Atlantic EEZ.

### **Status**

The Western North Atlantic Stock of harbor seals is not considered strategic under the MMPA; this species is not listed as threatened or endangered under the ESA and is not listed under the MA ESA. Harbor seals have been experiencing a UME since July of 2018, with elevated mortalities across Maine, New Hampshire, and Massachusetts (NOAA Fisheries, 2019d). There were 2,954 seal strandings (primarily harbor and gray seals, but also some harp and hooded seals) between July 1, 2018 and September 25, 2019 with 914 strandings in Massachusetts. Evidence so far suggests phocine distemper virus as the cause of the strandings.

## **5.0 TYPE OF INCIDENTAL TAKING AUTHORIZATION REQUESTED**

Mayflower is requesting an IHA pursuant to section 101(a)(5)(D) of the MMPA for incidental take by Level B harassment of small numbers of marine mammals during the site characterization survey activities described in Sections 1 and 2 in and around OCS-A 0521 and along an export cable route to Falmouth, MA (Figure 1).

Site characterization surveys have the potential to take marine mammals by “Level B” harassment as a result of sound energy introduced to the marine environment. In the absence of mitigation measures, sounds that may “harass” marine mammals include pulsed sounds generated by the HRG survey equipment including the sub-bottom profiler and sparker. The potential effects will depend on the species of marine mammal, the behavior of the animal at the time of reception of the stimulus, as well as the received level (RL) of the sound. Disturbance reactions are likely to vary among some of the marine mammals in the general vicinity of the sound source. No Level A “take” by serious injury is reasonably expected, given the nature of the specified activities and the mitigation measures that are planned.

## **6.0 TAKE ESTIMATES FOR MARINE MAMMALS**

All anticipated takes would be “takes by harassment”, involving temporary changes in behavior (i.e., Level B harassment). That is, acoustic exposure could result in temporary displacement of marine mammals

from within ensonified zones or other temporary changes in behavioral state. The mitigation measures to be applied will reduce the already very low probability of Level A takes to the point of being discountable. The planned geophysical surveys are not expected to “take” more than small numbers of marine mammals and will have a negligible effect on the affected species or stocks. In the sections below, we describe methods to estimate “take by harassment” and present estimates of the numbers of marine mammals that might be affected during the planned activities.

### **6.1. Basis for Estimating Potential “Take”**

The amount of potential “take by harassment” is calculated in this section by multiplying the expected densities of marine mammals in the survey area by the area of water likely to be ensonified by geophysical survey equipment above the applicable NMFS defined thresholds. The estimated numbers are based on the densities (individuals per unit area) of marine mammals expected to occur in the survey area in the absence of survey activities. The take estimates presented herein are likely overestimates of the numbers of animals exposed to a specified level of sound because marine mammals tend to move away from anthropogenic sounds before the sound level reaches the criterion level and tend not to approach operating survey equipment. The area of water exposed to sounds above threshold levels is based on previously reported measurement and modeling data for the same or similar geophysical survey equipment planned for use by Mayflower and the extent and duration of the planned surveys, as described below.

### **6.2. Acoustic Thresholds**

To assess potential auditory injury, Level A harassment, NMFS has established technical guidance (NMFS 2018) that establishes dual criteria for five different marine mammal hearing groups, four of which occur in the Lease Area (

Table 5. Marine mammal functional hearing groups and Level A thresholds as defined by NMFS (2018) for species present in the survey area.). Scientific recommendations for revisions to these classifications were recently published by Southall et al. (2019), but have not yet been incorporated into the NMFS guidelines.

The received level at which marine mammals may behaviorally respond to anthropogenic sounds varies by numerous factors including the frequency content, predictability, and duty cycle of the sound as well as the experience, demography and behavioral state of the marine mammals (Southall et al. 2007; Ellison et al. 2012). Despite this variability, there is a practical need for a reasonable and specific threshold. NMFS currently defines the threshold for behavioral harassment, Level B take, as 160 dB re 1  $\mu$ Pa SPL<sub>rms</sub> [unless otherwise noted, all dB values hereafter are referenced to 1  $\mu$ Pa] for impulsive or intermittent sounds such as those produced by the HRG survey equipment to be used during the planned survey.

Table 5. Marine mammal functional hearing groups and Level A thresholds as defined by NMFS (2018) for species present in the survey area.

Marine Mammal Hearing Group	Generalized Hearing Range	Acoustic Thresholds
Low-frequency cetaceans (LF)	7 Hz to 35 kHz	$L_{pk,flat}$ : 219 dB $L_{E,LF,24h}$ : 183 dB
Mid-frequency cetaceans (MF)	150 Hz to 160 kHz	$L_{pk,flat}$ : 230 dB $L_{E,LF,24h}$ : 185 dB
High-frequency cetaceans (HF)	275 Hz to 160 kHz	$L_{pk,flat}$ : 202 dB $L_{E,LF,24h}$ : 155 dB
Phocid pinnipeds (underwater) (PW)	50 Hz to 86 kHz	$L_{pk,flat}$ : 218 dB $L_{E,LF,24h}$ : 185 dB

### 6.3. Area Potentially Exposed to Sounds above Threshold Levels

As described in Section 1.2 of this request, only some of the in-water equipment planned for use during this survey produces sounds audible to marine mammals. This includes the sub-bottom profiler, sparker, and USBL systems (Table 1). The USBL systems are necessary for navigational and equipment positioning purposes which are activities for which NMFS does not require authorization, so they are not considered further in this section. Equipment that operates in the water but outside the range of marine mammal hearing, at or above 200 kHz, includes the multi-beam echosounders and sidescan sonars, none of which are considered further in this section.

#### 6.3.1. Level A

Table 6 provides details on the geophysical survey equipment planned for use by Mayflower that may result in the taking of marine mammals. Methods used to estimate distances to threshold levels are described in Appendix A. The calculations are based on a combination of manufacturer provided source levels and operational parameters for the specific equipment as well as source level and directional measurements of similar equipment reported by Crocker and Fratantonio (2016).

The Innomar SES-2000 sub-bottom profiler has the highest source level of the planned equipment, but it operates at relatively high frequencies with most energy focused in a narrow beam. It also has a very high repetition rate (40 pulses per second) which places it into the intermittent (non-impulsive) source category. Altogether, this results in very short distances to Level A thresholds for all hearing groups except the high-frequency cetaceans, for which the  $SEL_{cum}$  distance is 60 m (Table 6).

As a conservative approach, the GeoMarine Geo-Source 400 tip sparker was assumed to be an omnidirectional source. Therefore, even with a much lower source level, the distance to the high-frequency cetacean  $SEL_{cum}$  threshold was estimated to be 8 m (Table 6). Distances to  $SPL_{peak}$  thresholds from the sparker source were 4 m or less.

The largest distance to a Level A threshold from any source is anticipated to be 60 m for high-frequency cetaceans and less than 1 m for all other hearing groups (Table 6). The only high-frequency cetacean species present in this region is the harbor porpoise. Harbor porpoise are known to largely avoid vessels and anthropogenic sounds; thus, even in the absence of the mitigation measures proposed in Section 11, the potential for Level A harassment of this or any other species is very unlikely. Therefore, no Level A takes are expected or are being requested.

Table 6. Estimated distances to Level A take thresholds for the planned survey equipment.

Equipment Type	Representative System	Operating Frequency (kHz)	Source Level	Distance (m) to Level A Threshold (pk / cum)				
				LFC	MFC	HFC	PPW	OPW
Medium Penetration	Innomar SES-2000	85 – 115	247 dB <sub>peak</sub>	NA / <1	NA / <1	NA / 60	NA / <1	NA / <1
	Medium- 100 parametric		241 dB <sub>rms</sub>					
Sub-bottom Profiler	EdgeTech 3100 with SB- 216 towfish	2 – 16	184 dB <sub>peak</sub>	- / <1	- / <1	- / 3	- / <1	- / <1
Medium Penetration Sparker	Geo-Source 200/400 w/ 400 tip sparker - 800 J	0.25 – 5	213 dB <sub>peak</sub>	- / <1	- / <1	4 / 8	- / <1	- / <1

“NA” Not Applicable as there are no SPL<sub>peak</sub> threshold criteria for intermittent sources.

“-“ Indicates the HRG equipment source level is below the relevant threshold level.

### 6.3.2. Level B

In July, 2019, NMFS issued interim recommendations for calculating distances to the 160 dB SPL<sub>rms</sub> Level B threshold from HRG sources (NMFS 2019b). The recommendations provided specific equations for incorporating absorption loss at higher frequencies and accounting for narrow beamwidths and angles when calculating transmission loss from equipment source levels. Due to substantial variability in back-propagated source levels calculated from field verification measurements received by NMFS, the recommendations also stated that source levels in Crocker and Fratantonio (2016) should be used when the same equipment measured in that study are planned for use. If different makes or models of similar equipment are used, then the guidance stated that manufacturer provided source levels should be used in the calculations. The following sections summarize the parameters used to estimate the 160 dB SPL<sub>rms</sub> threshold range for each piece of equipment based on the July 2019 NMFS guidance including additional adjustments for seawater absorption and out-of-beam or side-lobe energy produced by the equipment as described in Appendix B.

#### Sub-bottom profilers

Crocker and Fratantonio (2016) measured source levels of an EdgeTech SB-512i sub-bottom profiler (operational frequencies 0.5–12 kHz) controlled by an EdgeTech 3200-XS topside processor. Mayflower plans to use a similar EdgeTech topside processor (EdgeTech 3100) paired with a different, but very similar, sub-bottom profiler towfish that operates at slightly higher frequencies (2–16 kHz). The highest measured source level for the EdgeTech SB-512i at 100% power with the frequency band set to 2–12 kHz was 179 dB SPL<sub>rms</sub> and a beamwidth of 65° (Crocker and Fratantonio 2016). Since the topside processor and frequency range settings used during these measurements were very similar to those planned for use by Mayflower, this measurement is considered a reasonable surrogate for the planned survey equipment. Using the 179 dB SPL<sub>rms</sub> source level and the recommended adjustments for frequency and beamwidth, the calculated horizontal distance to the 160 dB SPL<sub>rms</sub> threshold is 5 m (Table 7; Appendix B).

The Innomar SES-2000 sub-bottom profiler was not measured by Crocker and Fratantonio (2016), so manufacturer-provided specifications were used to calculate the range to the 160 dB SPL<sub>rms</sub> threshold. As shown in Table 2, the Innomar SES-2000 sub-bottom profiler operates in two different frequency bands, with primary frequencies in the 85–115 kHz range and secondary frequencies in the 2–22 kHz range. The manufacturer-stated source level for the primary frequencies is 247 dB SPL<sub>peak</sub>. The average difference between sub-bottom profiler SPL<sub>peak</sub> and SPL<sub>rms</sub> source levels reported by Crocker and Fratantonio (2016) was 6 dB. Therefore, we assumed an SPL<sub>rms</sub> source level of 241 dB. The source level for the secondary

frequencies is approximately 40 dB lower, or 203 dB SPL<sub>rms</sub>. Using the 241 dB SPL<sub>rms</sub> source level and the recommended adjustments for frequency (85 kHz) and beamwidth (2°), the calculated horizontal distance to the 160 dB SPL<sub>rms</sub> threshold for in-beam sounds is 14 m. However, when the out-of-beam energy is treated as an omnidirectional source, it results in a 160 dB SPL<sub>rms</sub> distance of 116 m (Table 7; Appendix B).

**Sparkers**

Crocker and Fratantonio (2016) did not measure the sparker system planned for use during this project; however, the GeoMarine Geo-Source 400 tip sparker planned for use by Mayflower likely produces very similar sounds as the SIG ELC 820 sparker that was measured by Crocker and Fratantonio (2016). The measured source level of the SIG ELC 820 sparker at 5 m water depth with an input voltage of 750 J was 203 dB SPL<sub>rms</sub> (Table 9 in Crocker and Fratantonio (2016)). Using this source level and assuming it is an omnidirectional source (180° beamwidth), the calculated horizontal distance to the 160 dB SPL<sub>rms</sub> threshold is 141 m (Table 7; Appendix B).

Table 7. Estimated distances to Level B take thresholds for the planned survey equipment.

Equipment Type	Representative System	Operating Frequency (kHz)	Source Level (dB rms)	Out-of-Beam Source Level (dB rms)	Beamwidth (degrees)	Distance to Level B Threshold (m)
Medium Penetration	Innomar SES-2000	85 – 115	241	241	2	116
Sub-bottom Profiler	Medium- 100 parametric					
	EdgeTech 3100 with SB- 216 towfish	2 – 16	179	179	65	5
Medium Penetration Sparker	Geo-Source 200/400 w/ 400 tip sparker - 800 J	0.25 – 5	203	N/A	180	141

**Ensonified Area**

The largest distance to the 160 dB SPL<sub>rms</sub> Level B threshold is expected to be 141 m from the 800 J sparker. This distance was used as described in this section to estimate the area of water potentially exposed above the Level B threshold by the planned activities.

As shown in Table 1, up to 16,775 km of survey activity may occur from June through September 2020, including turns between lines or occasional testing of equipment while not collecting geophysical data. For the purposes of calculating take, the HRG survey activities have been split into two different areas, 1) the lease area plus the deep-water portion of the cable route, and 2) the shallow water portion of the cable route including very shallow water sections of the cable route.

Within the Lease Area and deep-water portion of the cable route, the vessel will conduct surveys at a speed of approximately 3 knots (5.6 km/hr) during 24-hr operations. Allowing for occasional weather and equipment downtime, the survey vessel is expected to cover a maximum average distance of 110 km per day. During 90 days of anticipated activity over the 4 month period (approximately 22.5 survey days per month), this means up to 9,900 km may be traveled while the HRG equipment is operating. Using a 160 dB SPL<sub>rms</sub> threshold distance of 141 m, the total daily ensonified area is estimated to be 31.1 km<sup>2</sup>, or an average of 699.4 km<sup>2</sup> each month within the Lease Area and deep-water portion of the cable route.

Along the shallow-water portion of the cable route, including in very shallow waters, survey vessels will also conduct surveys at a speed of approximately 3 knots (5.6 km/hr), but only during daylight hours. Allowing for occasional weather and equipment downtime, the survey vessels are each expected to cover a maximum average distance of approximately 55 km per day. During 125 days of anticipated activity over the 4 month period (approximately 31.3 total survey days per month split among two survey vessels), this means up to 6,875 km may be traveled while the HRG equipment is operating. Using a 160 dB SPL<sub>rms</sub> threshold distance of 141 m, the total daily ensonified area is estimated to be 15.6 km<sup>2</sup>, or an average of 486.6 km<sup>2</sup> each month along the shallow-water cable route.

#### **6.4. Marine Mammal Densities**

Density estimates for the three survey areas were derived from habitat-based density modeling results reported by Roberts et al. (2016, 2017, 2018). Those data provide abundance estimates for species or species guilds within 10 km x 10 km grid cells (100 km<sup>2</sup>) on a monthly or annual basis, depending on the species. In order to select a representative sample of grid cells in and near the survey areas, a 10-km wide perimeter around the lease area and an 8-km wide perimeter around the cable route were created in GIS (ESRI 2017). The perimeters were then used to select grid cells near the survey areas containing the most recent monthly or annual estimates for each species in the Roberts et al. (2016, 2017, 2018) data. The average monthly abundance for each species in each survey area was calculated as the mean value of the grid cells within each survey area in each month and then converted to density (individuals / 1 km<sup>2</sup>) by dividing by 100 km<sup>2</sup> (Table 8, Table 9).

The estimated monthly density of seals provided in Roberts et al. (2018) includes all seal species present in the region as a single guild. Based upon a recommendation from NMFS, we did not separate this guild into the individual species based on the proportion of sightings identified to each species within the dataset because so few of the total sightings used in the Roberts et al. (2018) analysis were actually identified to species (Table 8, Table 9).

Table 8. Average monthly densities for species that may occur in the Lease Area and along the deep-water section of the cable route during the planned survey period.

Species	Estimated Monthly Densities (Individuals/km <sup>2</sup> )			
	Jun	Jul	Aug	Sep
<i>Mysticetes</i>				
Fin Whale*	0.0032	0.0033	0.0029	0.0025
Humpback Whale	0.0014	0.0011	0.0005	0.0011
Minke Whale	0.0024	0.0010	0.0007	0.0008
North Atlantic Right Whale*	0.0012	0.0000	0.0000	0.0000
Sei Whale*	0.0002	0.0001	0.0000	0.0001
<i>Odontocetes</i>				
Atlantic White-Sided Dolphin	0.0628	0.0446	0.0243	0.0246
Common Bottlenose Dolphin	0.0249	0.0516	0.0396	0.0494
Harbor Porpoise	0.0188	0.0125	0.0114	0.0093
Pilot Whales	0.0066	0.0066	0.0066	0.0066
Risso's Dolphin	0.0002	0.0005	0.0009	0.0007
Short-Beaked Common Dolphin	0.0556	0.0614	0.1069	0.1711
Sperm Whale*	0.0001	0.0004	0.0004	0.0002
<i>Pinnipeds</i>				
Seals (Harbor and Gray)	0.0260	0.0061	0.0033	0.0040

\* Denotes species listed under the Endangered Species Act

Table 9. Average monthly densities for species that may occur along the shallow-water section of the cable route during the planned survey period.

Species	Estimated Monthly Densities (Individuals/km <sup>2</sup> )			
	Jun	Jul	Aug	Sep
<i>Mysticetes</i>				
Fin Whale*	0.0003	0.0003	0.0003	0.0003
Humpback Whale	0.0001	0.0001	0.0000	0.0001
Minke Whale	0.0002	0.0000	0.0000	0.0000
North Atlantic Right Whale*	0.0000	0.0000	0.0000	0.0000
Sei Whale*	0.0000	0.0000	0.0000	0.0000
<i>Odontocetes</i>				
Atlantic White-Sided Dolphin	0.0010	0.0006	0.0005	0.0008
Common Bottlenose Dolphin	0.2308	0.4199	0.3211	0.3077
Harbor Porpoise	0.0048	0.0023	0.0037	0.0036
Pilot Whales	0.0000	0.0000	0.0000	0.0000
Risso's Dolphin	0.0000	0.0000	0.0000	0.0000
Short-Beaked Common Dolphin	0.0003	0.0002	0.0006	0.0009
Sperm Whale*	0.0000	0.0000	0.0000	0.0000
<i>Pinnipeds</i>				
Seals (Harbor and Gray)	0.2496	0.0281	0.0120	0.0245

\* Denotes species listed under the Endangered Species Act

### 6.5. Requested Take

The potential numbers of Level B takes were calculated by multiplying the monthly density for each species in each survey area shown in Table 8 and Table 9 by the respective monthly ensonified area within each survey area (see Section 6.3). The results are shown in the “Calculated Take” columns of Table 10.

The survey area estimates were summed to produce the “Total Calculated Take” and then rounded up to arrive at the number of “Requested Takes” for each species (Table 10). For four species, North Atlantic right whale, sei whale, Risso’s dolphin, and sperm whale, the Requested Take column reflects a rounding up of the mean group size calculated from survey data in this region (Kraus et al. 2016; Palka et al. 2017). The requested number of Level B takes as a percentage of the “best available” abundance estimates provided in the NMFS Stock Assessment Reports (Hayes et al. 2019) as well as those reported by Roberts et al. (2016, 2017, 2018) are also provided in Table 10. For the “Seal” guild, composed of both gray and harbor seals, the lower estimated abundance for gray seals is shown in Table 10. When assessed against the combined take from both species, this results in the highest estimated percentage of either seal species’ population potentially exposed. No Level A takes are requested.

Bottlenose dolphins encountered in the survey area would likely belong to the Western North Atlantic Offshore Stock (Hayes et al. 2019). However, it is possible that a few animals encountered during the surveys could be from the North Atlantic Northern Migratory Coastal Stock, but they generally do not range farther north than New Jersey. Also, based on the distributions described in Hayes et al. (2019), pilot whale sightings in the survey area would most likely be long-finned pilot whales, although short-finned pilot whales could be encountered in the survey area during the summer months.

Table 10. Number of Level B takes requested and percentages of each stock abundance.

Species	Calculated Take by Survey Region		Total Calculated Take	Requested Take	Abundance NMFS <sup>a</sup>	Abundance Roberts <sup>b</sup>	Percent of NMFS <sup>a</sup> Stock Abundance	Percent of Roberts <sup>b</sup> Abundance
	Lease Area & Deep Water Cable Route	Shallow Water Cable						
<i>Mysticetes</i>								
Fin Whale*	8.3	0.6	8.9	9	1,618	3,005	0.6	0.3
Humpback Whale	2.9	0.2	3.1	4	896	1,773	0.4	0.2
Minke Whale	3.4	0.2	3.6	4	2,591	3,014	0.2	0.1
North Atlantic Right Whale*	0.9	0.0	0.9	3	451	394	0.7	0.8
Sei Whale*	0.3	0.0	0.3	2	357	453	0.6	0.4
<i>Odontocetes</i>								
Atlantic White-Sided Dolphin	109.3	1.4	110.7	111	48,819	91,473	0.2	0.1
Common Bottlenose Dolphin	115.7	622.6	738.3	739	77,532	75,620	1.0	1.0
Harbor Porpoise	36.4	7.0	43.4	44	79,833	60,281	0.1	0.1
Pilot Whales	18.4	0.0	18.4	19	34,560	27,597	0.1	0.1
Risso's Dolphin	1.7	0.0	1.7	6	18,250	11,483	0.0	0.1
Short-Beaked Common Dolphin	276.3	1.0	277.2	278	70,184	121,292	0.4	0.2
Sperm Whale*	0.8	0.0	0.8	2	2,288	4,199	0.1	0.0
<i>Pinnipeds</i>								
Seals (Harbor and Gray)	40.4	152.8	193.2	194	27,131	1,435	0.7	13.5

\* Denotes species listed under the Endangered Species Act.

<sup>a</sup> Source – Hayes et al. (2019); The “Seal” abundance value shown is for gray seals, which has the lower abundance of the two species.

<sup>b</sup> Source – Roberts et al. (2016, 2017, 2018); The “Seal” abundance value shown is for gray seals, which has the lower abundance of the two species.

For North Atlantic right whales, the implementation of a 500 m acoustic exclusion zone and the 500 m vessel separation distance identified in the vessel strike avoidance measures means that the likelihood of an exposure to received sound levels greater than 160 dB SPL<sub>rms</sub> is very low. In addition, most of the survey activity will take place during the time of year when right whales are unlikely to be present in this region. Nonetheless, it is possible that North Atlantic right whales could occur within 500 m of the vessel without first being detected by a PSO, so we have requested the calculated potential take consistent with other species.

## 7.0 ANTICIPATED IMPACT OF THE ACTIVITY

All marine mammals use sound as a critical way to carry out life-sustaining functions, such as foraging, navigating, communicating, and avoiding predators. Marine mammals also use sound to learn about their surrounding environment by gathering information from other marine mammals, prey species, phenomena such as wind, waves, and rain, and from seismic activity (Richardson et al. 1995). The effects of sounds from HRG surveys could include either masking of natural sounds or behavioral disturbance (Richardson et al. 1995; Nowacek et al. 2007; Southall et al. 2007).

Behavioral disturbance includes a variety of effects, ranging from subtle to conspicuous changes in behavior, movement and respiration patterns as well as displacement (Southall et al. 2007). In some cases, behavioral responses to sound may result in a reduction of the overall exposure to that sound (e.g., Finneran et al. 2015; Wensveen et al. 2015).

Detailed data on reactions of marine mammals to anthropogenic sounds are limited to relatively few species and situations (see reviews by Richardson et al. 1995; Gordon et al. 2004; Nowacek et al. 2007; Southall et al. 2007). Behavioral reactions of marine mammals to sound are difficult to predict in the absence of site- and context-specific data. Reactions to sound, if any, depend on species, state of maturity, experience, current activity, reproductive state, time of day, exposure level, spectral content and directionality of the sound, and many other factors (Richardson et al. 1995; Wartzok et al. 2004; Southall et al. 2007; Weilgart 2007; Ellison et al. 2012). If a marine mammal reacts to an underwater sound by changing its behavior or moving a small distance, the impacts of the change are unlikely to be significant to the individual, let alone the stock or population (e.g., New et al. 2013a). However, if a sound source displaces marine mammals from an important feeding or breeding area for a prolonged period, impacts on individuals and populations could be significant (Lusseau and Bejder 2007; Weilgart 2007; Nowacek et al. 2015; New et al. 2013b; Forney et al. 2017).

Masking is the obscuring of sounds of interest by interfering sounds, generally at similar frequencies. Introduced underwater sound will, through masking, reduce the effective listening area and/or communication distance of a marine mammal species if the frequency of the source is close to that used as a signal by the marine mammal, and if the anthropogenic sound is present for a significant fraction of the time (Richardson et al. 1995; Clark et al. 2009; Jensen et al. 2009; Gervaise et al. 2012; Hatch et al. 2012; Rice et al. 2014; Erbe et al. 2016; Tenessen and Parks 2016). Conversely, if little or no overlap occurs between the introduced sound and the frequencies used by the species, communication is not expected to be disrupted. Also, if the introduced sound is present only infrequently, communication is not expected to be disrupted much, if at all. In addition to the frequency and duration of the masking sound, the strength, temporal pattern, and location of the introduced sound also play a role in the extent of the masking (Branstetter et al., 2013, 2016; Finneran and Branstetter, 2013; Sills et al., 2017). Loss of listening area or communication space could impact foraging success or result in the inability to locate conspecifics. The biological repercussions of these potential outcomes are largely unknown, but given the operating frequencies and source levels of the HRG equipment, significant impacts from masking are not expected.

Some of the HRG survey equipment proposed for use during the site characterization surveys produces sounds with frequency ranges similar to those of marine mammal hearing and vocalizations and thus could result in masking of some biologically important sounds. The impulsive nature of these sounds,

limited duration of the survey activities, and short distances over which they would be audible suggest that any masking experience by marine mammals would be localized and short term.

Given the many uncertainties in predicting the quantity and types of impacts of sound on marine mammals, it is common practice to estimate how many animals would be present within a particular distance of human activities and/or exposed to a particular level of anthropogenic sound (see Section 6). In most cases, this approach likely overestimates the numbers of marine mammals that would be affected in some biologically important manner. One of the reasons for this is that the selected distances/isopleths are based on limited studies indicating that some animals exhibited short-term reactions at this distance or sound level, whereas the calculation assumes that all animals exposed to this level would react in a biologically significant manner.

The most likely behavioral change exhibited by marine mammals as a result of HRG survey activities would be displacement, or moving away from the sound. It is presumed that displacement, if it were to occur, would be limited to the area surrounding the sound source that is ensonified to above the Level B thresholds of 160 dB SPL<sub>rms</sub> for impulsive sounds, and would only last for the duration that the sound source is active, with animals resuming regular behavior once the sound source ceases.

## **8.0 ANTICIPATED IMPACTS ON SUBSISTENCE USES**

The Mayflower Lease Area survey activities will take place off the NE coast of the United States in the Atlantic Ocean. There are no traditional subsistence hunting areas in the region and thus no subsistence uses of marine mammals may be impacted by this action.

## **9.0 ANTICIPATED IMPACTS ON HABITAT**

The altered soundscape resulting from sounds produced during HRG survey activities would be short term and localized, and would not permanently alter marine mammal acoustic habitat.

Collection of vibracore, seabed CPT, and borehole samples during geotechnical surveys would disturb benthic habitat where samples are taken and could impact water quality via sediment resuspension and dispersion. These impacts would be short term and localized to the immediate vicinity around sample sites within a large area of similar habitat. Permanent impacts to marine mammal habitat are not anticipated.

## **10.0 ANTICIPATED EFFECTS OF HABITAT IMPACTS ON MARINE MAMMALS**

The altered soundscape in the vicinity of HRG survey activities could result in masking of sounds important to marine mammals or displacement of individuals from the survey area. Masking would only occur within relatively short distances while survey activities are underway and thus would be temporary and localized to the vicinity of the survey activities. It is expected that any displacement of marine mammals from the survey area would also be temporary and localized. Displaced individuals would be able to access areas of similar habitat near the area impacted by the survey activity.

## **11.0 MITIGATION MEASURES TO PROTECT MARINE MAMMALS AND THEIR HABITAT**

The following monitoring and mitigation measures apply to vessels conducting the geophysical surveys as described in Section 1.1 for which takes have been requested in Section 6. Any vessel conducting HRG surveys on a 24-hr per day basis (i.e. including during darkness) will have 6 PSOs and a PAM system on board to carry out the necessary monitoring. Any vessel conducting HRG survey activities only during daylight hours will have 2 PSOs on board and no PAM system. Takes are not anticipated for vessels when they are conducting geotechnical surveys, so the monitoring and mitigation measures described here will not apply during those activities.

### **11.1. Protected Species Monitoring**

A team of four Protected Species Observers (PSOs) and two Passive Acoustic Monitoring (PAM) operators will be used to undertake visual and acoustic watches, implement mitigation measures, and conduct data collection and reporting in accordance with the survey plan and the requirements in the IHA and the BOEM OCS-A 0521 lease conditions. All PSOs will have completed a BOEM and NMFS accepted PSO training program as described in BOEM NTL 2016-G02. PSOs will have relevant observation experience in the Atlantic or Gulf of Mexico. In addition, PAM Operators will also have completed an appropriate training course. All PSOs and PAM operators will be approved by NMFS prior to the start of survey operations. Upon completion of the project, Mayflower will provide a final report and data to NMFS.

#### **11.1.1. PSO/PAM Watch Guidelines**

One PSO will be on watch at all times during daylight HRG and geotechnical operations. Two PSOs will be on watch at all times during nighttime HRG and geotechnical operations. No additional duties will be assigned to PSOs during their visual observation watches. PSOs and PAM operators will work in shifts such that no one observer works more than 4 consecutive hours without a 2-hour break or longer than 12 hours during any 24-hour period.

#### **11.1.2. Day-time Visual Monitoring Equipment**

All PSOs will be supplied with reticle binoculars to assist in making detections and estimating ranges. A digital SLR camera will be provided to record detection events, when possible, and verify species identification.

#### **11.1.3. Night-time Visual Monitoring Equipment**

The PSOs on duty will monitor for marine mammals and other protected species using night-vision goggles with thermal clip-ons and a hand-held spotlight (one set plus a back-up set), such that PSOs can focus observations in any direction.

#### **11.1.4. Passive Acoustic Monitoring**

One PAM operator will be on watch during nighttime and periods of reduced visibility, such as fog. The PAM system is designed to provide a flexible approach to the monitoring for marine mammals using a towed hydrophone system. The system uses PAMGUARD software modules such that the optimum system can be configured for the application, vessel, and deployment method. The source vessel will have two acoustic monitoring systems installed, a primary system and a secondary system available as back-up should any issues be encountered with the main system. The PAM operator will be proficient in its use and PAM will be deployed and functional for use during periods of reduced visibility (including nighttime and

day-time fog when exclusion zones are obscured) in order to meet the acoustic monitoring requirements of the survey plan.

The PAM system will be considered to be non-functioning for the purposes of mitigation monitoring if the PAM cable is damaged such that monitoring cannot be undertaken using at least two of the hydrophones, where one must be a low-frequency hydrophone capable of detecting the vocalizations of North Atlantic right whales; the PAM computer is damaged or unable to load or run the acoustic monitoring software properly; the acoustic monitoring software is not functioning; or sea conditions are too rough for deployment of the hydrophone array.

Acoustic detections will be communicated to the lead PSO on duty so that any necessary mitigation measures can be implemented.

### 11.1.5. Data Collection and Reporting

PSOs will collect data in accordance with standard reporting forms, software tools, and electronic data forms. These data will be summarized in a report describing the observation effort, sightings, and the extent and nature of potential takes within 90-days of survey completion.

### 11.1.6. Mitigation Measures

Proposed mitigation measures for use during the Mayflower site characterization survey activities are described in the following sections.

#### Exclusion Zones

Acoustic exclusion zones to prevent Level A takes are typically established at the estimated Level A threshold distances. Using this approach, acoustic exclusion zones applicable to marine mammals within each hearing group would be established based on results in Appendix A as follows:

- Low-frequency cetaceans = 1 m
- Mid-frequency cetaceans = 1 m
- High-frequency cetaceans = 60 m
- Phocid pinnipeds in water = 1 m
- Otariid pinnipeds in water = 1 m

Thus, a single exclusion zone of 1 m would be appropriate for all marine mammal species except high-frequency cetaceans. For high-frequency cetaceans (harbor porpoise), an exclusion zone of 60 m would be appropriate.

However, the BOEM lease agreement for the OCS-A 0521 Lease Area requires the following “Default Exclusion Zones” (Addendum C Section 4.3.6.1):

- 500 m separation distance from North Atlantic right whales as per vessel strike avoidance measures (see next section).
- 200 m exclusion zone for ESA-listed whales and sea turtles.
- 100 m exclusion zone for harbor porpoise and humpback whales (in the absence of an Incidental Take Authorization (ITA) from NMFS).
- 50 m exclusion zone for all other non-listed marine mammals (in the absence of an ITA from NMFS).

Upon issuance of an IHA the following exclusion zones would be implemented based on an appropriate combination of the two sets of exclusion zones listed above:

- 500 m exclusion zone for North Atlantic right whales
- 60 m exclusion zone for harbor porpoise

- 10 m exclusion zone for all other marine mammals

Besides the planned 500 m acoustic exclusion zone for North Atlantic right whales, the implementation of the 500 m separation distance from North Atlantic right whales based on the vessel strike avoidance rules will create an effective acoustic exclusion zone of 500 m for this species.

### **Pre-Startup Observations**

PSOs will conduct observations of the 200 m exclusion zone for a minimum of 60 minutes prior to the start of sound sources operating at frequencies <200 kHz and continue until 30 minutes following cessation of sound source use. If a marine mammal, or other protected species, is observed within or approaching the appropriate exclusion zone during the pre-start period, survey equipment will not be activated until the animal(s) is confirmed by visual observation to have exited the relevant exclusion zone, or until an additional time period has elapsed with no further sighting of the animal (15 minutes for small delphinids and pinnipeds, 30 minutes for all other marine mammals, and 60 minutes for sea turtles).

### **Ramp-up**

When technically feasible, a “ramp-up” of the electromechanical survey equipment will occur at the start or re-start of HRG survey activities. A ramp-up would begin with the power of the lowest power acoustic equipment for the HRG survey at its lowest power output. The power output would be gradually turned up and other acoustic sources added in a way such that the source level would increase in steps not exceeding 6 dB per 5-minute period.

### **Shut-downs**

Anytime a protected species is sighted within the applicable exclusion zone the PSO will call for an immediate shutdown of the survey equipment. However, HRG survey equipment may continue to operate if marine mammals voluntarily approach the vessel (e.g. to bow ride) when the sound sources are at full operating power. During the day, if the exclusion zone around the source equipment is not completely visible, the sound sources must be shut down OR a PAM operator must begin acoustic monitoring to augment the visual observations during that period of reduced visibility.

If the HRG equipment shuts down for reasons other than encroachment into the exclusion zone, resulting in the cessation of the HRG equipment for a period of greater than 20 minutes, restart of the survey equipment will only commence after clearance of the exclusion zone and implementation of ramp-up procedures. If the pause is less than 20 minutes the equipment will be restarted as soon as practicable at its previous operational level as long as visual surveys were continued throughout the silent period and the exclusion zone remained clear of marine mammals.

### **11.1.7. Vessel Strike Avoidance**

A number of measures intended to reduce the chance of vessels striking and injuring marine mammals and other protected species, such as sea turtles and giant manta rays, will be implemented while operating in the region in support of Mayflower's site characterization surveys. These measures include:

- Maintaining a vigilant watch for marine mammals and other protected species and slowing down or stopping vessels to avoid striking protected species.
- Complying with speed restrictions ( $\leq 10$  knots) in North Atlantic right whale management areas including critical habitat, Seasonal Management Areas (SMAs), and active Dynamic Management Areas (DMAs).
- Reducing speed of vessels  $\geq 65$  feet in length to  $\leq 10$  knots between November 1 through July 31.

- Monitoring the NMFS North Atlantic Right whale reporting systems from the start of the surveys between November 1 through July 31, and during other times if a DMA is established in the operational area.
- Operate vessel at a speed of 10 knots or less in any DMA.
- Reducing vessel speeds to  $\leq 10$  knots when mother/calf pairs, pods, or large assemblages of marine mammals are observed.
- Maintaining  $>500$  m distance from North Atlantic right whales or an unidentified large marine mammal; if a right whale comes within 100 m, then reducing speed and shifting the engines into neutral, if safe to do so.
- Maintaining  $>100$  m from all ESA-listed marine mammals.
- If underway, the vessel must reduce speed and shift the engine to neutral, and must not engage the engines until the whale (e.g., large whale and/or ESA-listed whales besides NARW) has moved beyond 100 m.
- Maintaining  $>50$  m from all other marine mammals, with the exception of delphinids and pinnipeds that approach the vessel, in which case the vessel operator must avoid excessive speed or abrupt changes in direction.
- Report sightings of all dead or injured marine mammals or sea turtles within 24 hrs.

#### **11.1.8. Sound Source Verification**

In 2019, NMFS expressed concerns with HRG sound source verification measurements previously collected in offshore wind leases in the Northeast and recommended developers requesting incidental take authorization to estimate zones of potential acoustic impact using standard modeling guidance (NMFS 2019b). Mayflower Wind did not conduct SSV measurements for 2019 surveys and does not plan to collect SSV measurements as part of the planned 2020 surveys.

## **12.0 MITIGATION MEASURES TO PROTECT SUBSISTENCE USES**

Not applicable. There are no subsistence uses of marine mammals impacted by this action.

## **13.0 MONITORING AND REPORTING**

Planned monitoring activities have been described in Section 11 along with the associated mitigation measures. A marine mammal sighting and detection report will be provided to NMFS as required by authorization stipulations.

Sightings of any NARW will be reported to the RWSAS as soon as it is practical to do so. Sightings of any injured, distressed, or dead marine mammals will be reported by a PSO to NMFS as soon as it is practical to do so and in accordance with any requirements set forth in the IHA.

## **14.0 SUGGESTED MEANS OF COORDINATION**

Mayflower will coordinate the planned marine mammal monitoring program associated with the seismic survey off the U.S. east coast (as summarized in § XI and XIII) with other parties that may have

interest in the area and/or be conducting marine mammal studies in the same region during the proposed seismic survey.

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## **APPENDIX A – DISTANCES TO LEVEL A ACOUSTIC THRESHOLDS**



# **Distances to Acoustic Thresholds corresponding to Level A Injury for High Resolution Geophysical Sources**

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**Mayflower Wind HRG**

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## Contents

1. METHODS.....	3
2. SOURCES.....	5
2.1. Sparker.....	6
2.2. Sub-bottom Profiler .....	7
3. DISTANCES.....	9
3.1. Sparker.....	9
3.2. Sub-bottom Profiler .....	9
4. SUMMARY .....	9
LITERATURE CITED .....	11
APPENDIX A. EQUIPMENT SPECIFICATION REFERENCE SHEETS.....	A-1

# 1. Methods

This section describes the methods used to estimate the horizontal distances to the National Marine Fisheries Service (NMFS) acoustic thresholds for injury (Table 1). There are different thresholds for impulsive and non-impulsive (intermittent) sounds. According to Southall et al. (2007), “Harris (1998) proposed a measurement-based distinction of pulses and non-pulses that is adopted here in defining sound types. Specifically, a ≥ 3-dB difference in measurements between continuous and impulse [sound level meter] setting indicates that a sound is a pulse; a < 3-dB difference indicates that a sound is a non-pulse. We note the interim nature of this distinction for underwater signals and the need for an explicit distinction and measurement standard such as exists for aerial signals (ANSI, 1986).”

All the Mayflower Wind pulse durations are ≤ 10 ms. A single pulse of short duration ( $T \ll 35$  ms – the impulse setting averaging time) would always be considered a pulse using the Southall et al. (2007) criterion. For multiple pulses of short duration, the same reasoning holds if they are separated by an interval well in excess of either 125 ms (8 Hz repetition rate) or 1000 ms (1 Hz repetition rate), depending on whether a fast (125 ms) or slow (1000 ms) time constant is used. If the repetition rate is high enough (> 8 Hz, which we round to 10 Hz to be conservative) the multiple pulses effectively merge together and become one long non-impulse using the same Southall et al (2007) criterion, irrespective of the choice of time constant.

Thus, sources that operate with a repetition rate greater than 10 Hz were assessed with the non-impulsive (intermittent) source criteria; sources with a repetition rate equal to or less than 10 Hz were assessed with the impulsive source criteria.

Table 1. Peak sound pressure level (PK, dB re 1 μPa) and sound exposure level (SEL, dB re 1 μPa<sup>2</sup>·s) thresholds for injury (PTS onset) for marine mammals for impulsive and non-impulsive sound sources (NMFS 2018).

Functional hearing group	Impulsive source		Non-impulsive (intermittent) source
	PK	Weighted SEL <sub>24h</sub>	Weighted SEL <sub>24h</sub>
Low-frequency cetaceans (LFC)	219	183	199
Mid-frequency cetaceans (MFC)	230	185	198
High-frequency cetaceans (HFC)	202	155	173
Phocid pinnipeds in water (PPW)	218	185	201
Otariid pinnipeds in water (OPW)	232	203	219

NMFS provides a spreadsheet to calculate these distances, but it is not designed for high-resolution geophysical survey sources. The spreadsheet does not consider seawater absorption or beam patterns, both of which can substantially influence received sound levels. In order to account for these effects, we model sound levels using Equations 1–9, as follows.

The sonar equation is used to calculate the received sound pressure level:

$$SPL(r) = SL - PL(r), \tag{1}$$

where  $SPL$  is the sound pressure level (dB re 1 μPa),  $r$  is the distance from the source (m),  $SL$  is the source level (dB re 1 μPa m), and  $PL$  is the propagation loss as a function of distance. Propagation loss is calculated using:

$$PL(r) = 20\log_{10}\left(\frac{r}{1\text{ m}}\right) \text{ dB} + \alpha(f) \cdot r/1000, \tag{2}$$

where  $\alpha(f)$  is the absorption coefficient (dB/km) and  $f$  is frequency (kHz). The absorption coefficient is approximated by discarding the boric acid term from Ainslie (2010; p29; eq 2.2):

$$\alpha(f) \approx 0.000339f^2 + 48.5f^2/(75.6^2 + f^2). \quad (3)$$

When a range of frequencies is produced by a source, we use the lowest frequency for determining the absorption coefficient.

The source level is either its in-beam value (for angles within the -3 dB beamwidth) or a single representative out-of-beam value. This representative value is estimated by first calculating upper and lower bounds and then taking the average of these. We assume the beam pattern  $b(u)$  is that of an unshaded circular transducer:

$$b(u) = (2 J_1(u)/u)^2, \quad (4)$$

where  $J_1(u)$  is a first order Bessel function of the first kind, whose argument is a function of off-axis angle  $\theta$  and beam width (full width at half maximum)  $\delta\theta$

$$u = u_0 \frac{\sin \theta}{\sin \frac{\delta\theta}{2}}, \quad (5)$$

where  $u_0 = 1.614$ .

For the upper limit we choose the highest sidelobe level of the beam pattern, given by (Ainslie 2010; p265; Table 6.2)

$$B_{\max} = -17.6 \text{ dB}. \quad (6)$$

For the lower limit we consider the asymptotic behaviour of the beam pattern in the horizontal direction

$$J_1(u) \sim \sqrt{\frac{2}{\pi u}} \cos\left(u - \frac{3\pi}{4}\right), \quad (7)$$

where

$$u = \frac{u_0}{\sin \frac{\delta\theta}{2}}. \quad (8)$$

In this way we obtain the lower limit as

$$B_{\min} = 10 \log_{10} \left( \frac{8}{\pi u_0^3} \sin^3 \frac{\delta\theta}{2} \right) \text{ dB}. \quad (9)$$

The out-of-beam source level is found by adding the arithmetic mean of  $B_{\min}$  and  $B_{\max}$  to the in-beam source level.

For broad beam sources (beam widths larger than  $90^\circ$ ), we assumed the source was omnidirectional. For intermediate beam sources (beam widths between  $36^\circ$  and  $90^\circ$ ), we interpolated the correction between the two methods. The resulting correction as a function of beam width is shown in Figure 1.

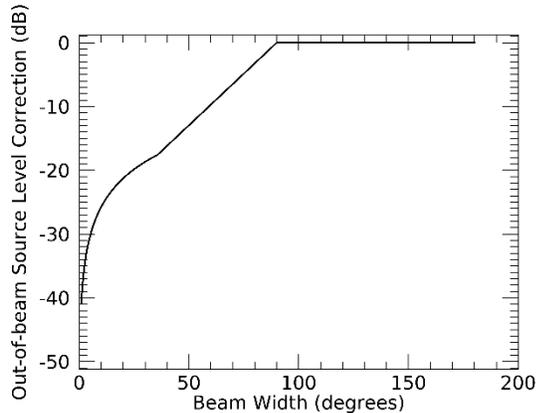


Figure 1. Correction for calculating out-of-beam source level (i.e., in the horizontal direction) from in-beam source level, as a function of source beam width.

Separate sound levels were calculated using the in-beam source level at the angle corresponding to the - 3 dB half-width and the out-of-beam source level in the horizontal direction. The higher of the two sound levels was then selected for assessing impact distance.

Distances to peak thresholds were calculated using the peak source level and applying propagation loss from Equation 2. Peak levels were assessed for both in-beam and out-of-beam levels (the latter was assessed using the out-of-beam source level correction described previously).

For the weighted SEL thresholds, we performed the following steps:

1. Calculated weighted broadband energy source levels (ESL) by assuming a flat spectrum between the source minimum and maximum frequency, weighted the spectrum according to the marine mammal hearing group weighting function (NMFS 2018), and summed across frequency.
2. Modeled propagation loss as a function of oblique range using Equation 2.
3. Modeled per-pulse SEL for a stationary receiver at a fixed distance off a straight survey line, using a vessel transit speed of 3.5 knots and source-specific pulse length and repetition rate. The off-line distance is referred to as the closest point of approach (CPA) and was performed for CPA distances between 1 m and 10 km. The survey line length was modeled as 10 km long (analysis showed longer survey lines increased SEL by a negligible amount). SEL is calculated as  $SPL + 10 \log_{10} \frac{T}{1s}$  dB, where T is the pulse duration. For equipment where ESL was known, we used ESL directly in the calculations and provide the corresponding pulse duration, calculated from  $T = 10^{[(ESL - SL)/10]}$ , in Section 2. Both in-beam and out-of-beam levels were included in the SEL calculation as per the described method above.
4. Calculated the SEL for each survey line to produce curves of weighted SEL as a function of CPA distance.
5. Used the curves from Step 4 to estimate the CPA distance to the threshold.

This method accounts for the hearing sensitivity of the marine mammal group, seawater absorption, and beam width for downwards-facing transducers.

## 2. Sources

The following subsections describe the source characteristics of HRG equipment that operates at and below 200 kHz ([BOEM] Bureau of Ocean Energy Management 2014). The horizontal impact distance to

the Level A threshold (Table 1) was computed for each source by applying the methods from Section 1. We used the following conservative assumptions when calculating impact distances:

- For sources that operate at different levels (power settings) we used the maximum source level provided in Crocker and Fratantonio 2016 or manufacturer specifications.
- For sources that operate with different beam widths, we used the maximum beam width.
- We use the lowest frequency of the source when calculating the absorption coefficient.

## 2.1. Sparker

Mayflower Wind plans to use the Geomarine Geo-Spark Ultra Hi-Res Sparker System with 400 tip Geo-Source and a maximum source energy of 800 J. Under the direction of NMFS, source specifications in Crocker and Fratantonio (2016) for the SIG ELC 820 Sparker were used as a proxy for this system (750 J energy setting for 5 m source depth). Repetition rate was provided by Mayflower Wind. The frequency range was estimated from the 3 dB bandwidth reported in Crocker and Fratantonio (2016). The frequency range represents the largest bandwidth reported in Table 9 of Crocker and Fratantonio (2016).

Table 2. Sparker source specifications.

Equipment	Frequency (kHz)	Source Level (dB re 1 $\mu$ Pa m)	Peak Source Level (dB re 1 $\mu$ Pa m)	Energy source level (dB re 1 $\mu$ Pa <sup>2</sup> s m <sup>2</sup> )	Beam Width <sup>a</sup> (°)	Pulse Duration (ms)	Repetition Rate (Hz)
Geomarine Geo-Spark 400 tip operating at 800 J	0.25 – 5	203	213	178	180	3.4	2

<sup>a</sup>Multi-tip sparkers are typically activated simultaneously to direct energy downwards and so they should have a downwards-oriented directivity pattern. We have not been able to find published directivity information for sparkers so have conservatively assumed sparker sources are omnidirectional. This assumption will likely lead to a larger estimated horizontal impact distance than would be expected during operation.

Table 3. References for sparker specifications in Table 2.

Equipment	Frequency (kHz)	Source Level (dB re 1 $\mu$ Pa m)	Peak Source Level (dB re 1 $\mu$ Pa m)	Energy source level (dB re 1 $\mu$ Pa <sup>2</sup> s m <sup>2</sup> )	Beam Width (°)	Pulse Duration (ms)	Repetition Rate (Hz)
Geomarine Geo-Spark 400 tip operating at 800 J	Estimated from the 3 dB bandwidth reported in Crocker and Fratantonio (2016)	SIG ELC 820 Sparker, 5 m source depth, 750 J setting (see Table 9 in Crocker and Fratantonio (2016))			Assumed omnidirectional	SIG ELC 820 Sparker, 5 m source depth, 750 J setting (see Table 9 in Crocker and Fratantonio (2016))	Provided by Mayflower Wind

## 2.2. Sub-bottom Profiler

Table 4. Sub-bottom profiler source specifications. Table 5 lists the corresponding references.

Equipment	Frequency (kHz)	Source Level (dB re 1 $\mu\text{Pa m}$ )	Peak Source Level (dB re 1 $\mu\text{Pa m}$ )	Energy source level (dB re 1 $\mu\text{Pa}^2\text{s m}^2$ )	Beam Width ( $^\circ$ )	Pulse Duration (ms)	Repetition Rate (Hz)
Edgetech 3100 with SB-216 towfish	2 – 16	179	184	159	65	10	10
Innomar SES-2000 Medium-100 parametric	85 – 115	241	247	214	2	0.07 – 2	40

Table 5. References for sub-bottom profiler source specifications in Table 4.

Equipment	Frequency (kHz)	Source Level (dB re 1 $\mu$ Pa m)	Peak Source Level (dB re 1 $\mu$ Pa m)	Energy source level (dB re 1 $\mu$ Pa <sup>2</sup> s m <sup>2</sup> )	Beam Width (°)	Pulse Duration (ms)	Repetition Rate (Hz)
Edgetech 3100 with SB-216 towfish	Manufacturer specification sheet or manual (Sect. A.2)	Considered EdgeTech Chirp 512i as a proxy for source levels as the Chirp 512i has similar operation settings as the Chirp 216 (Appendix A.2). See Table 18 in Crocker and Fratantonio (2016) for 100 % power and 2-12 kHz	Considered EdgeTech Chirp 512i as a proxy for source levels as the Chirp 512i has similar operation settings as the Chirp 216 (Appendix A.2). See Table 18 in Crocker and Fratantonio (2016) for 100 % power and 2-12 kHz	Considered EdgeTech Chirp 512i as a proxy for source levels as the Chirp 512i has similar operation settings as the Chirp 216 (Appendix A.2). See Table 18 in Crocker and Fratantonio (2016) for 100 % power and 2-12 kHz	Considered EdgeTech Chirp 512i as a proxy for source levels as the Chirp 512i has similar operation settings as the Chirp 216 (Appendix A.2). Conservative estimate for the higher-frequency 216 towfish based on the lower frequency 512i measurements in Crocker and Fratantonio (2016), Table 20.	Calculated from the difference between source level and energy source level (ref. Section 1 step 3)	Provided by Mayflower Wind
Innomar SES-2000 Medium-100 parametric	Manufacturer specification sheet or manual (Sect. A.1)	Specification sheet (Sect. A.2) indicates peak source level of 247 dB re 1 $\mu$ Pa m (Jens Wunderlich, Innomar, personal communication, 2019-07-18). Average difference between source level and peak source level for sub-bottom profilers measured by Crocker and Fratantonio (2016) was 6 dB. We therefore estimate source level is 241 dB re 1 $\mu$ Pa m, 6 dB less than the peak source level.	Manufacturer specification sheet or manual (Sect. A.2). Jens Wunderlich (Innomar, personal communication, 2019-07-18) indicates this is peak source level.	Calculated from pulse duration and source level	Manufacturer specification sheet or manual (Sect. A.2)	Manufacturer specification sheet or manual (Sect. A.2).	Manufacturer specification sheet or manual (Sect. A.1).

### 3. Distances

The following tables list the geophysical survey sources and the horizontal impact distances to the Level A thresholds that were obtained by applying the methods from Section 1 with the source parameters in Section 2. The Innomar sub-bottom profiler was assessed based on the intermittent SEL thresholds because of the relatively high repetition rate (40 Hz); all other sources were assessed with the impulsive SEL and peak thresholds.

#### 3.1. Sparker

Table 6. Level A horizontal impact distances for sparkers.

Equipment	Level A horizontal impact distance (m) to PK threshold					Level A horizontal impact distance (m) to SEL threshold				
	LFC	MFC	HFC	PPW	OPW	LFC	MFC	HFC	PPW	OPW
Geomarine Geo-Spark 400 tip operating at 800 J	—	—	4	—	—	1	<1	8	<1	<1

— Source level is less than threshold level.

#### 3.2. Sub-bottom Profiler

Table 7. Level A horizontal impact distances for sub-bottom profilers.

Equipment	Level A horizontal impact distance (m) to PK threshold					Level A horizontal impact distance (m) to SEL threshold				
	LFC	MFC	HFC	PPW	OPW	LFC	MFC	HFC	PPW	OPW
Edgetech 3100 with SB-216 towfish	—	—	—	—	—	<1	<1	3	<1	<1
Innomar SES-2000 Medium-100 parametric	NA	NA	NA	NA	NA	<1	<1	60	<1	<1

— Source level is less than threshold level.

NA - Distances to the PK thresholds are not shown for the Innomar because it was assessed based on the intermittent source criteria which does not include PK thresholds (Table 1).

### 4. Summary

The table below lists the equipment that was associated with the largest horizontal impact distance for each equipment type.

Table 8. Summary of Level A horizontal impact distances.

Equipment	System	Level A horizontal impact distance (m)				
		LFC	MFC	HFC	PPW	OPW
Sparker	Geomarine Geo-Spark 400 tip operating at 800 J	1	<1	8	<1	<1
Sub-bottom Profiler	Innomar SES-2000 Medium-100 parametric	<1	<1	60	<1	<1

The methods used here are approximate and likely conservative. A rigorous propagation loss model coupled with a full beam pattern and spectral source model would result in more accurate results. Assessing the accuracy of either method requires sound field measurements.

---

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## Appendix A. Equipment Specification Reference Sheets

### A.1. Innomar Sub-bottom Profiler



► **Performance**

- water depth range: 2–2,000 m
- penetration: up to 70 m, depending on sediments
- layer resolution: up to 5 cm
- motion compensation: heave, roll
- beam width @ 3 dB:  $\pm 1^\circ$  / footprint < 3.5% of water depth for all frequencies

► **Transmitter**

- primary frequencies: approx. 100 kHz (band 85 – 115 kHz)
- secondary low frequencies: 4, 5, 6, 8, 10, 12, 15 kHz (band 2 – 22 kHz)
- primary source level: >247 dB/ $\mu$ Pa re 1 m
- pulse width: 0.07–2 ms
- pulse rate: up to 40/s
- multi-ping mode
- pulse type: CW, Ricker, LFM (chirp)

► **Acquisition**

- primary frequency (echo sounder, bottom track)
- secondary low frequency (sub-bottom data, multi-frequency mode)
- sample rate 96 kHz @ 24 bit

► **System Components**

- transceiver unit 19 inch / 12U (WHD: 0.52 m x 0.58 m x 0.40 m; 56 kg)
- transducer incl. 30 m cable (WHD: 0.50 m x 0.12 m x 0.50 m; 60 kg)
- system control: internal PC
- KVM remote control

## SES-2000 medium-100 Parametric Sub-bottom Profiler

► **Software**

- SESWIN data acquisition software
- SES Convert SEG-Y/XTF data export
- SES NetView remote display
- ISE post-processing software

► **Power Supply Requirements**

- 100–240V AC / 50–60 Hz
- power consumption: <700 W





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## A.2. Edgetech Sub-bottom Profilers

### 2.0 SPECIFICATIONS

2-2

#### 2.1.2 Processor Unit Specs

The specifications for the Processing Unit within the rack mount topside are shown in **TABLE 2-2**.

SPECIFICATION	VALUE
<b>Mother Board</b>	Intel I7 6700 Quad Core 3.4GHz. 8 MB Cache
<b>Sonar Interface</b>	Sonar Interface board (Tiger board) composed of carrier board, Acquisition board, and Sonar board
<b>Memory</b>	8 GB DDR4 RAM
<b>Hard Drives</b>	500 GB minimum (operating system) 1 TB minimum (Removable Drive [Hot Swappable])
<b>DVD-R/W drive</b>	10x4x32 minimum speed
<b>Operating system</b>	Windows 7 64 Bit
<b>Application software</b>	DISCOVER Sub-Bottom
<b>Display</b>	High resolution 23-inch flat panel LCD monitor
<b>Keyboard</b>	High impact industrial
<b>Trackball</b>	High impact industrial
<b>I/O ports</b>	(4) RS-232 Front: (2) Ethernet Ports (2) USB2 Rear: (2) USB2 (2) USB3 (2) USB3.1
<b>Analog input</b>	16-bit resolution, 200 kHz max sampling rate
<b>Analog Output</b>	16-bit resolution, 200 kHz max sampling rate
<b>Pulse type</b>	Full Spectrum CHIRP FM
<b>Pulse length</b>	5-100 ms, depending on tow vehicle and application
<b>Bandwidth</b>	0.5-15 kHz, depending on tow vehicle and application
<b>Trigger in</b>	TTL negative edge triggered
<b>Trigger out</b>	TTL negative edge triggered, 5ms ling pulse minimum
<b>Sampling rate</b>	20, 25, 40, or 50 kHz, depending on the transmit upper frequency
<b>Acoustic power</b>	212 dB re1 NPa @ 1 meter peak (approx.) at center frequency
<b>Input voltage</b>	120-220 VAC, 50/60 Hz, auto sense

Table 2-2: 3200-XS Topside Processor Specs

#### 2.1.3 Power Amplifier

The specifications for the Power Amplifier are show in **TABLE 2-5**, **TABLE 2-4**, and **TABLE 2-5**.

##### 2.1.3.1 Power Output

SPECIFICATION	VALUE
<b>2-ohm Dual (per channel)</b>	20 mS BURST: 4,700 W 20 Hz – 20 kHz: 2,800 W 1 kHz: 2,800 W
<b>4-ohm Dual (per channel)</b>	3,500 W
<b>8-ohm Dual (per channel)</b>	1,500 W
<b>4-ohm Bridge</b>	5,600 W
<b>8-ohm Bridge</b>	6,000 W

Table 2-3: Power Amplifier Specs: Power Output

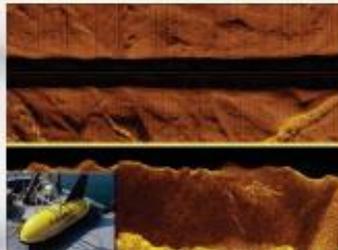


# 2000 SERIES

COMBINED SIDE SCAN SONAR & SUB-BOTTOM PROFILING SYSTEM

## KEY SPECIFICATIONS

SIDE SCAN SONAR			
Frequency (dual simultaneous CHIRP)	100/400 kHz		300/600 kHz
Operating Range	100 kHz: 500 meters/side 400 kHz: 150 meters/side		300 kHz: 230 meters/side 600 kHz: 120 meters/side
Beam Width (2-way) & Along Track Resolution	100 kHz: 1.08 deg or 1.90 m @ 100 m 400 kHz: 0.56 deg or 0.96 m @ 100 m		300 kHz: 0.6 deg or 1.0 m @ 100 m 600 kHz: 0.26 deg 0.45 m @ 100 m
Across Track Resolution	100 kHz: 6.3 cm 400 kHz: 1.8 cm		300 kHz: 2.8 cm 600 kHz: 1.4 cm
SUB-BOTTOM PROFILER			
	2000-CSS	2000-DSS	2000-TVD
Frequency Band	500 Hz - 12 kHz	2-16 kHz	1-10 kHz
Resolution	8-20 cm	6-10 cm	9-25 cm
Penetration in coarse sand	20m	6m	20m
Penetration in clay	200m	80m	200m
TOWFISH			
	2000-CSS	2000-DSS	2000-TVD
Length	160 cm (63")	145 cm (57")	226 cm (89")
Width	124 cm (49")	74 cm (30")	81 cm (32")
Height	47 cm (18.5")	84 cm (33")	55 cm (22")
Weight in Air	232 kg (510 lbs.)	145 kg (320 lbs.)	250 kg (550 lbs.)
Maximum Water Depth	300m	2,000m	3000m
TOPSIDE PROCESSOR			
Hardware	Standard 19" rack		
Operating System	Windows XP		
Display	Dual 22" high resolution flat panel monitors		
Archive	DVD-R/W and/or LAN connection		
File Format	Native JSF or XTF for side scan, SEG-Y for sub-bottom		
Output	Ethernet		
Power Input	90 to 132 VAC and 180 to 260 VAC, Auto voltage detect and switching, 47-63 Hz		



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SPECIFICATION	SB-424 VALUE	SB-216S VALUE	SB-512i VALUE
Frequency range	4-24 kHz	2-16 kHz	0.5-12 kHz
Pulse type	FM	FM	FM & WB (wide band)
Pulse bandwidth/pulse length	4-24 kHz/10 ms 4-20 kHz/10 ms 4-16 kHz/10 ms	2-15 kHz/20 ms 2-12 kHz/20 ms 2-10 kHz/20 ms	0.5-8.0 kHz/5 ms FM 0.5-2.7 kHz/40 ms WB 0.5-6.0 kHz/20 ms WB 0.5-4.5 kHz/50 ms FM 0.5-6.0 kHz/9 ms FM 0.5-6.0 kHz/18 ms FM 0.5-7.2 kHz/30 ms FM 0.7-12.0 kHz/20 ms FM 2.0-12.0 kHz/20 ms FM
Calibration:	Gaussian-shaped pulse spectrum	Gaussian-shaped pulse spectrum	Gaussian- and rectangular-shaped pulse spectrum
Vertical resolution <sup>a</sup>	4 cm (4-24 kHz) 6 cm (4-20 kHz) 8 cm (4-16 kHz)	6 cm (2-15 kHz) 8 cm (2-12 kHz) 10 cm (2-10 kHz)	19 cm (1-5.0 kHz) 12 cm (1.5-7.5 kHz) 8 cm (2-12 kHz)
Penetration in coarse and calcareous sand <sup>b</sup>	2 m (typ)	6 m (typ)	30 m (typ)
Penetration in soft clay <sup>b</sup>	40 m	80 m	250 m
Beam width	16°, 4-24 kHz 19°, 4-20 kHz 23°, 4-16 kHz	17°, 2-15 kHz 20°, 2-12 kHz 24°, 2-10 kHz	41°, 0.5-5 kHz 32°, 1-6 kHz 24°, 1.5-7.5 kHz 16°, 2-12 kHz
Optimum tow vehicle pitch/roll <sup>c</sup>	<7°, 4-24 kHz <8°, 4-20 kHz <10°, 4-16 kHz	<7°, 2-15 kHz <8°, 2-12 kHz <10°, 2-10 kHz	<16°, 0.5-5 kHz <13°, 1-6 kHz <10°, 2-8 kHz <8°, 2-10 kHz <7°, 2-12 kHz
Optimum tow height	3-5m above sea floor	3-5 m above sea floor	3-5 m above sea floor
Transmitters	1	1	2
Receive arrays	2	2	4
Output power	2000 W	2000W	2000 W
Tow vehicle size	77 cm (30 in.) L 50 cm (20 in.) W 34 cm (13 in.) H	105 cm (41 in.) 67 cm (26 in.) W 46 cm (18 in.) H	158 cm (62 in.) L 134 cm (53 in.) W 46 cm (18 in.) H
Shipping container size	91 cm (36 in.) L 66 cm (26 in.) W 64 cm (25 in.) H	117 cm (46 in.) L 79 cm (31 in.) W 61 cm (24 in.) H	173 cm (68 in.) L 137 cm (54 in.) W 71 cm (28 in.) H
Weight in air	35 kg (78 lb)	72 kg (160 lb)	186 kg (410 lb)
Shipping weight	110 kg (243 lb)	162 kg (357 lb)	356 kg (783 lb)
Tow cable requirements	3 shield-twisted wire pairs	3 shield-twisted wire pairs	3 shield-twisted wire pairs
Depth rating	300 m (984 ft) max	300 m (984 ft) max	300 m (984 ft) max

Table 2-6: Tow Vehicle Specifications

## **APPENDIX B – DISTANCES TO LEVEL B ACOUSTIC THRESHOLDS**



# **Distances to Acoustic Thresholds corresponding to Level B Harassment for High Resolution Geophysical Sources**

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**Mayflower Wind HRG**

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## Contents

1. METHODS.....	1
2. SOURCES AND DISTANCES TO THRESHOLD .....	3
2.1. Sparker.....	3
2.2. Sub-Bottom Profiler.....	4
3. SUMMARY .....	5
LITERATURE CITED .....	6
APPENDIX A. EQUIPMENT SPECIFICATION REFERENCE SHEETS.....	A-1

## 1. Methods

This section describes the methods used to estimate the horizontal distance to the root-mean-square sound pressure level (SPL) 160 dB re 1  $\mu\text{Pa}$  isopleth for the purposes of estimating Level B harassment ([NMFS] National Marine Fisheries Service (US) and [NOAA] National Oceanic and Atmospheric Administration (US) 2005). We use the methods specified in the Interim Recommendation for Sound Source Level and Propagation Analysis for High Resolution Geophysical (HRG) Sources (NOAA September 9, 2019), with modifications to use a more accurate seawater absorption formula and a method to account for energy emitted outside of the primary beam of the source. The method is described below.

The sonar equation is first used to calculate the in-beam distance at which 160 dB re 1  $\mu\text{Pa}$  is reached:

$$SPL(r) = SL - PL(r), \quad (1)$$

where  $SPL$  is the sound pressure level (dB re 1  $\mu\text{Pa}$ ),  $r$  is the slant range (m),  $SL$  is the in-beam source level (dB re 1  $\mu\text{Pa}$  m), and  $PL$  is the propagation loss as a function of distance. Propagation loss is calculated using:

$$PL(r) = 20 \log_{10} \left( \frac{r}{1 \text{ m}} \right) \text{ dB} + \alpha(f) \cdot r/1000, \quad (2)$$

where  $\alpha$  is the absorption coefficient (dB/km) and  $f$  is frequency (kHz). The absorption coefficient is approximated by discarding the boric acid term from Ainslie (2010; p29; eq 2.2):

$$\alpha(f) \approx 0.000339f^2 + 48.5f^2/(75.6^2 + f^2). \quad (3)$$

When a range of frequencies is produced by a source, we use the lowest frequency for determining the absorption coefficient.

For pulses of duration less than 100 ms, the source level is calculated twice, with two different averaging times, the first equal to the pulse duration and the second equal to 100 ms, the latter chosen to represent a typical integration time for marine mammal hearing (Kastelein et al. 2010). For constructing soundscapes relevant to marine mammal hearing, a report of the Consortium for Ocean Leadership ([COL] Consortium for Ocean Leadership 2018) also recommends this averaging time.

The pulse duration for some sources was unknown. For these sources, pulse duration was calculated from the difference between source level ( $SL$ ) and energy source level ( $ESL$ ) using:

$$T = 10^{(ESL-SL)/10}. \quad (4)$$

For a downwards-pointing source with a beamwidth less than  $180^\circ$ , the horizontal impact distance ( $R$ ) is calculated from the in-beam range using:

$$R = r \cdot \sin \left( \frac{\delta\theta}{2} \right), \quad (5)$$

where  $\delta\theta$  is the -3 dB beamwidth.

To account for energy emitted outside of the primary beam of the source, we estimate a single representative out-of-beam source level and propagate the sound horizontally. For narrow-beam sources (up to  $36^\circ$  beam width) the out-of-beam source level is estimated by first calculating upper and lower bounds and then taking the average of these. We assume the beam pattern  $b(u)$  is that of an unshaded circular transducer:

$$b(u) = (2 J_1(u)/u)^2, \quad (6)$$

where  $J_1(u)$  is a first order Bessel function of the first kind, whose argument is a function of off-axis angle  $\theta$  and beam width (full width at half maximum)  $\delta\theta$

$$u = u_0 \frac{\sin \theta}{\sin \frac{\delta\theta}{2}}, \quad (7)$$

where  $u_0 = 1.614$ .

For the upper limit we choose the highest sidelobe level of the beam pattern, given by (Ainslie 2010; p265; Table 6.2)

$$B_{\max} = -17.6 \text{ dB.} \tag{8}$$

For the lower limit we consider the asymptotic behaviour of the beam pattern in the horizontal direction

$$J_1(u) \sim \sqrt{\frac{2}{\pi u}} \cos\left(u - \frac{3\pi}{4}\right), \tag{9}$$

where

$$u = \frac{u_0}{\sin\frac{\delta\theta}{2}}. \tag{10}$$

In this way we obtain the lower limit as

$$B_{\min} = 10 \log_{10} \left( \frac{8}{\pi u_0^3} \sin^3 \frac{\delta\theta}{2} \right) \text{ dB.} \tag{11}$$

The out-of-beam source level is found by adding the arithmetic mean of  $B_{\min}$  and  $B_{\max}$  to the in-beam source level.

For broad beam sources (beam widths larger than 90°), we assumed the source was omnidirectional. For intermediate beam sources (beam widths between 36° and 90°), we interpolated the correction between the two methods. The resulting correction as a function of beam width is shown in Figure 1.

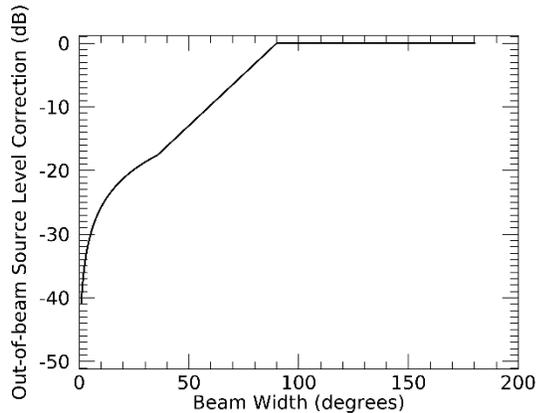


Figure 1. Correction for calculating out-of-beam source level (i.e., in the horizontal direction) from in-beam source level, as a function of source beam width.

Separate sound levels were calculated using the in-beam source level at the angle corresponding to the - 3 dB half-width and the out-of-beam source level in the horizontal direction. The higher of the two sound levels was then selected for assessing impact distance.

Both the pulse duration and 100 ms averaged source levels were used to compute two different horizontal impact distances for each source. These two distances were provided to show the effect of using a 100 ms averaging time, representative of marine mammal integration time (Kastelein et al., 2010). At the request of NMFS, the distances corresponding to the pulse duration averaged source levels were used in the summary section.

## 2. Sources and Distances to Threshold

The following subsections describe the source characteristics of HRG equipment that operates at and below 200 kHz ([BOEM] Bureau of Ocean Energy Management 2014). The horizontal impact distance to the Level B harassment threshold (160 dB re 1  $\mu$ Pa) was computed for each source by applying the methods from Section 1. We used the following conservative assumptions when calculating impact distances:

- For sources that operate with different beam widths, we used the maximum beam width.
- We use the lowest frequency of the source when calculating the absorption coefficient.

### 2.1. Sparker

Mayflower Wind plans to use the Geomarine Geo-Spark Ultra Hi-Res Sparker System with 400 tip Geo-Source and a maximum source energy of 800 J. Under the direction of NMFS, source specifications in Crocker and Fratantonio (2016) for the SIG ELC 820 Sparker were used as a proxy for this system (750 J energy setting for 5 m source depth). Repetition rate was provided by Mayflower Wind. The frequency range was estimated from the 3 dB bandwidth reported in Crocker and Fratantonio (2016). The frequency range represents the largest bandwidth reported in Table 9 of Crocker and Fratantonio (2016).

Table 1. Sparker specifications and Level B horizontal impact distance. See Table 2 for specification references.

Equipment	Frequency (kHz)	Source Level (dB re 1 $\mu$ Pa m)	Beam Width ( $^{\circ}$ ) <sup>a</sup>	Pulse Duration (ms)	Repetition Rate (Hz)	Level B Horizontal Impact Distance (m)	Adjusted source level for 100 ms Averaging Time (dB re 1 $\mu$ Pa m)	Level B Horizontal Impact Distance using 100 ms averaging time (m)
Geomarine Geo-Spark 400 tip operating at 800 J	0.25 – 5	203	180	3.4	2	141	188.3	26

<sup>a</sup>Multi-tip sparkers are typically activated simultaneously to direct energy downwards and so they should have a downwards-oriented directivity pattern. We have not been able to find published directivity information for sparkers so have conservatively assumed sparker sources are omnidirectional. This assumption will likely lead to a larger estimated horizontal impact distance than would be expected during operation.

Table 2. References for sparker specifications in Table 1.

Equipment	Frequency (kHz)	Source Level (dB re 1 $\mu$ Pa m)	Beam Width ( $^{\circ}$ )	Pulse Duration (ms)	Repetition Rate (Hz)
Geomarine Geo-Spark 400 tip operating at 800 J	Estimated from the 3 dB bandwidth reported in Crocker and Fratantonio (2016)	SIG ELC 820 Sparker, 5 m source depth, 750 J setting (see Table 9 in Crocker and Fratantonio (2016))	Assumed omnidirectional	SIG ELC 820 Sparker, 5 m source depth, 750 J setting (see Table 9 in Crocker and Fratantonio (2016))	Provided by Mayflower Wind

## 2.2. Sub-Bottom Profiler

Table 3 lists the sub-bottom profilers that are planned for Mayflower Wind HRG surveys, their associated specifications, and the Level B horizontal impact distances.

Table 3. Sub-bottom profiler specifications and Level B horizontal impact distances. See Table 4 for specification references.

Equipment	Frequency (kHz)	Source Level (dB re 1 $\mu$ Pa m)	Beam Width ( $^{\circ}$ )	Out-of-beam Source Level (dB re 1 $\mu$ Pa m)	Pulse duration (ms)	Repetition rate (Hz)	Level B Horizontal Impact Distance (m)	Adjusted source level for 100 ms averaging time (dB re 1 $\mu$ Pa m)	Level B Horizontal Impact Distance using 100 ms averaging time (m)
Edgetech 3100 with SB-216 towfish	2 – 16	179	65	170.9	10	10	5	169	2
Innomar SES-2000 Medium-100 parametric	85 – 115	241	2	204.7	2	40	116 <sup>a</sup>	230.0	42

<sup>a</sup>The horizontal impact distance was 14 m when the out-of-beam energy was ignored.

Table 4. References for sub-bottom profiler specifications in Table 3.

Equipment	Frequency (kHz)	Source Level (dB re 1 $\mu$ Pa m)	Beam Width (°)	Pulse Duration (ms)	Repetition Rate (Hz)
Edgetech 3100 with SB-216 towfish	Manufacturer specification sheet or manual (Sect. A.2)	Considered EdgeTech Chirp 512i as a proxy for source levels as the Chirp 512i has similar operation settings as the Chirp 216 (Appendix A.2). See Table 18 in Crocker and Fratantonio (2016) for 100 % power and 2-12 kHz	Considered EdgeTech Chirp 512i as a proxy for source levels as the Chirp 512i has similar operation settings as the Chirp 216 (Appendix A.2). Conservative estimate for the higher-frequency 216 towfish based on the lower frequency 512i measurements in Crocker and Fratantonio (2016), Table 20.	Calculated from the difference between energy source level and source level (see Table 18 in Crocker and Fratantonio (2016) for 100 % power and 2-12 kHz and Equation 4)	Provided by Mayflower Wind
Innomar SES-2000 Medium-100 parametric	Manufacturer specification sheet or manual (Sect. A.1)	Specification sheet (Sect. A.1) indicates peak source level of 247 dB re 1 $\mu$ Pa m (Jens Wunderlich, Innomar, personal communication, 2019-07-18). Average difference between source level and peak source level for sub-bottom profilers measured by Crocker and Fratantonio (2016) was 6 dB. We therefore estimate source level is 241 dB re 1 $\mu$ Pa m, 6 dB less than the peak source level.	Manufacturer specification sheet or manual (Sect. A.1)	Manufacturer specification sheet or manual (Sect. A.1).	Manufacturer specification sheet or manual (Sect. A.1).

### 3. Summary

For each equipment type, we compiled the equipment that produced the largest horizontal impact distance using the source levels averaged over the pulse duration. Table 5 lists the equipment and horizontal impact distances.

Table 5. Summary of Level B horizontal impact distances for different equipment types.

Equipment Type	Equipment with Largest Level B Horizontal Impact Distance	Level B Horizontal Impact Distance (m)
Sparker	Geomarine Geo-Spark 400 tip operating at 800 J	141
Sub-Bottom Profiler	Innomar SES-2000 Medium-100 parametric	116

We note that the methods used here are approximate and likely conservative. A rigorous propagation loss model coupled with a full beam pattern and spectral source model would result in more accurate results. Assessing the accuracy of either method requires sound field measurements.

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## Appendix A. Equipment Specification Reference Sheets

### A.1. Innomar Sub-bottom Profiler



**► Performance**

- water depth range: 2–2,000 m
- penetration: up to 70 m, depending on sediments
- layer resolution: up to 5 cm
- motion compensation: heave, roll
- beam width @ 3 dB:  $\pm 1^\circ$  / footprint < 3.5% of water depth for all frequencies

**► Transmitter**

- primary frequencies: approx. 100 kHz (band 85 – 115 kHz)
- secondary low frequencies: 4, 5, 6, 8, 10, 12, 15 kHz (band 2 – 22 kHz)
- primary source level: >247 dB/ $\mu$ Pa re 1 m
- pulse width: 0.07 – 2 ms
- pulse rate: up to 40/s
- multi-ping mode
- pulse type: CW, Ricker, LFM (chirp)

**► Acquisition**

- primary frequency (echo sounder, bottom track)
- secondary low frequency (sub-bottom data, multi-frequency mode)
- sample rate 96 kHz @ 24 bit

**► System Components**

- transceiver unit 19 inch / 12 U (WHD: 0.52 m x 0.58 m x 0.40 m; 56 kg)
- transducer incl. 30 m cable (WHD: 0.50 m x 0.12 m x 0.50 m; 60 kg)
- system control: internal PC
- KVM remote control

## SES-2000 medium-100 Parametric Sub-bottom Profiler

**► Software**

- SESWIN data acquisition software
- SES Convert SEG-Y/XTF data export
- SES NetView remote display
- ISE post-processing software

**► Power Supply Requirements**

- 100 – 240 V AC / 50 – 60 Hz
- power consumption: < 700 W





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## A.2. Edgetech Sub-bottom Profilers

### 2.0 SPECIFICATIONS

2-2

#### 2.1.2 Processor Unit Specs

The specifications for the Processing Unit within the rack mount topside are shown in **TABLE 2-2**.

SPECIFICATION	VALUE
<b>Mother Board</b>	Intel I7 6700 Quad Core 3.4GHz. 8 MB Cache
<b>Sonar Interface</b>	Sonar Interface board (Tiger board) composed of carrier board, Acquisition board, and Sonar board
<b>Memory</b>	8 GB DDR4 RAM
<b>Hard Drives</b>	500 GB minimum (operating system) 1 TB minimum (Removable Drive [Hot Swappable])
<b>DVD-R/W drive</b>	10x4x32 minimum speed
<b>Operating system</b>	Windows 7 64 Bit
<b>Application software</b>	DISCOVER Sub-Bottom
<b>Display</b>	High resolution 23-inch flat panel LCD monitor
<b>Keyboard</b>	High impact industrial
<b>Trackball</b>	High impact industrial
<b>I/O ports</b>	(4) RS-232 Front: (2) Ethernet Ports (2) USB2 Rear: (2) USB2 (2) USB3 (2) USB3.1
<b>Analog input</b>	16-bit resolution, 200 kHz max sampling rate
<b>Analog Output</b>	16-bit resolution, 200 kHz max sampling rate
<b>Pulse type</b>	Full Spectrum CHIRP FM
<b>Pulse length</b>	5-100 ms, depending on tow vehicle and application
<b>Bandwidth</b>	0.5-15 kHz, depending on tow vehicle and application
<b>Trigger in</b>	TTL negative edge triggered
<b>Trigger out</b>	TTL negative edge triggered, 5ms ling pulse minimum
<b>Sampling rate</b>	20, 25, 40, or 50 kHz, depending on the transmit upper frequency
<b>Acoustic power</b>	212 dB re1 NPa @ 1 meter peak (approx.) at center frequency
<b>Input voltage</b>	120-220 VAC, 50/60 Hz, auto sense

Table 2-2: 3200-XS Topside Processor Specs

#### 2.1.3 Power Amplifier

The specifications for the Power Amplifier are show in **TABLE 2-5**, **TABLE 2-4**, and **TABLE 2-5**.

##### 2.1.3.1 Power Output

SPECIFICATION	VALUE
<b>2-ohm Dual (per channel)</b>	20 mS BURST: 4,700 W 20 Hz – 20 kHz: 2,800 W 1 kHz: 2,800 W
<b>4-ohm Dual (per channel)</b>	3,500 W
<b>8-ohm Dual (per channel)</b>	1,500 W
<b>4-ohm Bridge</b>	5,600 W
<b>8-ohm Bridge</b>	6,000 W

Table 2-3: Power Amplifier Specs: Power Output



SPECIFICATION	SB-424 VALUE	SB-216S VALUE	SB-512i VALUE
Frequency range	4-24 kHz	2-16 kHz	0.5-12 kHz
Pulse type	FM	FM	FM & WB (wide band)
Pulse bandwidth/pulse length	4-24 kHz/10 ms 4-20 kHz/10 ms 4-16 kHz/10 ms	2-15 kHz/20 ms 2-12 kHz/20 ms 2-10 kHz/20 ms	0.5-8.0 kHz/5 ms FM 0.5-2.7 kHz/40 ms WB 0.5-6.0 kHz/20 ms WB 0.5-4.5 kHz/50 ms FM 0.5-6.0 kHz/9 ms FM 0.5-6.0 kHz/18 ms FM 0.5-7.2 kHz/30 ms FM 0.7-12.0 kHz/20 ms FM 2.0-12.0 kHz/20 ms FM
Calibration:	Gaussian-shaped pulse spectrum	Gaussian-shaped pulse spectrum	Gaussian- and rectangular-shaped pulse spectrum
Vertical resolution <sup>a</sup>	4 cm (4-24 kHz) 6 cm (4-20 kHz) 8 cm (4-16 kHz)	6 cm (2-15 kHz) 8 cm (2-12 kHz) 10 cm (2-10 kHz)	19 cm (1-5.0 kHz) 12 cm (1.5-7.5 kHz) 8 cm (2-12 kHz)
Penetration in coarse and calcareous sand <sup>b</sup>	2 m (typ)	6 m (typ)	30 m (typ)
Penetration in soft clay <sup>b</sup>	40 m	80 m	250 m
Beam width	16°, 4-24 kHz 19°, 4-20 kHz 23°, 4-16 kHz	17°, 2-15 kHz 20°, 2-12 kHz 24°, 2-10 kHz	41°, 0.5-5 kHz 32°, 1-6 kHz 24°, 1.5-7.5 kHz 16°, 2-12 kHz
Optimum tow vehicle pitch/roll <sup>c</sup>	<7°, 4-24 kHz <8°, 4-20 kHz <10°, 4-16 kHz	<7°, 2-15 kHz <8°, 2-12 kHz <10°, 2-10 kHz	<16°, 0.5-5 kHz <13°, 1-6 kHz <10°, 2-8 kHz <8°, 2-10 kHz <7°, 2-12 kHz
Optimum tow height	3-5m above sea floor	3-5 m above sea floor	3-5 m above sea floor
Transmitters	1	1	2
Receive arrays	2	2	4
Output power	2000 W	2000W	2000 W
Tow vehicle size	77 cm (30 in.) L 50 cm (20 in.) W 34 cm (13 in.) H	105 cm (41 in.) 67 cm (26 in.) W 46 cm (18 in.) H	158 cm (62 in.) L 134 cm (53 in.) W 46 cm (18 in.) H
Shipping container size	91 cm (36 in.) L 66 cm (26 in.) W 64 cm (25 in.) H	117 cm (46 in.) L 79 cm (31 in.) W 61 cm (24 in.) H	173 cm (68 in.) L 137 cm (54 in.) W 71 cm (28 in.) H
Weight in air	35 kg (78 lb)	72 kg (160 lb)	186 kg (410 lb)
Shipping weight	110 kg (243 lb)	162 kg (357 lb)	356 kg (783 lb)
Tow cable requirements	3 shield-twisted wire pairs	3 shield-twisted wire pairs	3 shield-twisted wire pairs
Depth rating	300 m (984 ft) max	300 m (984 ft) max	300 m (984 ft) max

Table 2-6: Tow Vehicle Specifications